

# Backward Error Analysis of Isospectral Integrators via Lie–Poisson Reduction of Butcher Series

Eugen BRONASCO, Klas MODIN

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# Incompressible Inviscid Fluid on a 2-Sphere

Equations for the velocity field  $\mathbf{v}(x, t)$  of an incompressible inviscid fluid,<sup>1</sup>

$$\frac{\partial \mathbf{v}}{\partial t} + \nabla_{\mathbf{v}} \mathbf{v} = -\nabla p, \quad \operatorname{div}(\mathbf{v}) = 0.$$

Consider the *vorticity* function  $\omega := \operatorname{curl}(\mathbf{v})$ , then,

$$\dot{\omega} + \{\psi, \omega\} = 0, \quad -\Delta \psi = \omega, \quad (1)$$

where  $\psi$  is called the *stream function* and  $\{\cdot, \cdot\}$  is the Poisson bracket on the sphere,<sup>2</sup>

Equation (1) is a *Lie–Poisson system* with the Hamiltonian given by the kinetic energy of the fluid,

$$H(\omega) = \frac{1}{2} \int_{\mathbb{S}^2} \omega (-\Delta)^{-1} \omega.$$

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<sup>1</sup>L. Euler. Principes généraux de l'état d'équilibre d'un fluide. Académie Royale des Sciences et des Belles-Lettres de Berlin, Mémoires, 11:217–273, 1757.

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# Matrix Hydrodynamics

The PDE for the vorticity  $\omega$ ,

$$\dot{\omega} + \{\psi, \omega\} = 0, \quad -\Delta\psi = \omega,$$

is discretized in space by the Euler-Zeitlin equation,

$$\dot{W} + \frac{1}{\hbar}[W, P] = 0, \quad -\Delta_d P = W,$$

where  $W \in \mathfrak{u}(d)$ .<sup>3</sup>

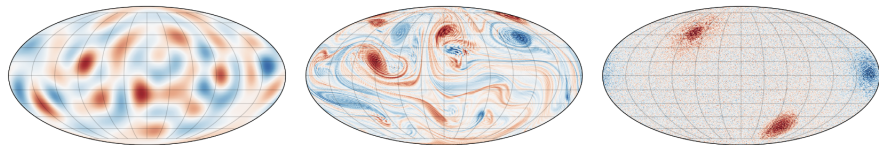
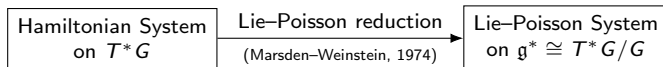


Figure: Vorticity field of a 2D fluid flow on a sphere.<sup>3</sup>

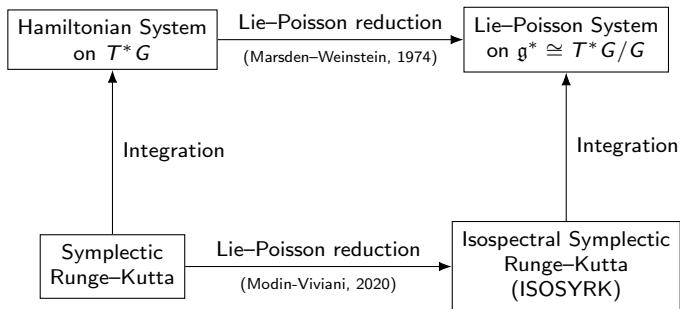
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<sup>3</sup>K. Modin and M. Viviani. Two-dimensional fluids via matrix hydrodynamics (arXiv:2405.14282).

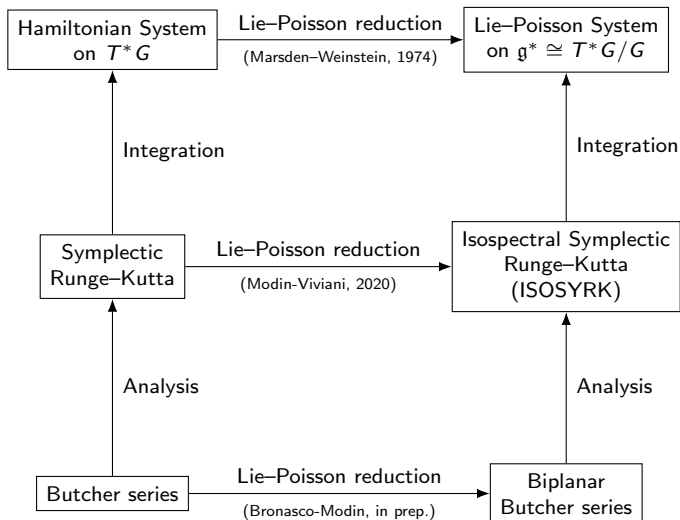
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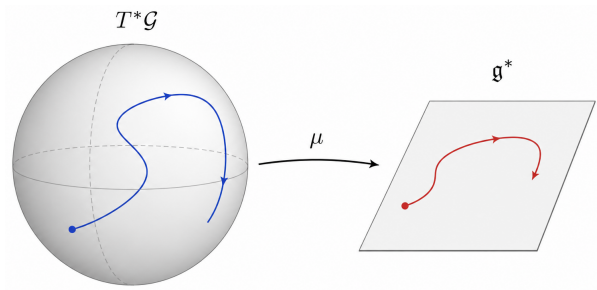


- 1 Lie–Poisson reduction and ISOSYRK methods
- 2 Biplanar Butcher series
  - 1 Biplanar forests and forest momentum map
  - 2 Biplanar Butcher series and Lie–Poisson reduction
  - 3 Composition and substitution laws
  - 4 Comparison with RKMK methods

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# Part 1

## Lie–Poisson reduction



Consider the following isospectral equation with linear  $f : \mathfrak{u}(d)^* \rightarrow \mathfrak{u}(d)^*$ ,

$$\dot{W} = \text{ad}_{f(W)}^*(W) = [f(W), W], \quad W(0) = W_0,$$

where we assume  $f(W) = \nabla H(W)^\dagger$  with the inner product on  $\mathfrak{u}(d)$  given by  $\langle A, B \rangle = \text{Tr}(A^\dagger B)$  and Hamiltonian  $H : \mathfrak{u}(d)^* \rightarrow \mathbb{R}$ .

The flow of this equation lives on the coadjoint orbit of  $U(d)$ ,

$$\mathcal{O}(W_0) := \{\text{Ad}_Q^* W_0 \mid Q \in U(d)\},$$

where  $\text{Ad}_Q^* W = QWQ^\dagger$  is the coadjoint action of  $U(d)$  on  $\mathfrak{u}(d)^* \cong \mathfrak{u}(d)$ .

Let the *momentum map*  $\mu : T^*U(d) \rightarrow \mathfrak{u}(d)^*$  be  $\mu(Q, P) := Q^\dagger P$ ,

$$\left. \begin{aligned} \dot{Q} &= Q \nabla H(Q^\dagger P) \\ \dot{P} &= -P \nabla H(Q^\dagger P)^\dagger \end{aligned} \right\} \mu_\# f.$$

is a Hamiltonian system on  $T^*U(d)$  with the Hamiltonian  $H \circ \mu$ .

The flow  $W(t)$  is given by  $W(t) = \mu(Q(t), P(t)) = Q(t)^\dagger P(t)$ .

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## Isospectral Symplectic Runge–Kutta methods

Consider a symplectic Runge–Kutta method  $(Q_n, P_n) \mapsto (Q_{n+1}, P_{n+1})$ , the corresponding ISOSYRK<sup>4</sup> method is obtained by

$$W_{n+1} = Q_{n+1}^\dagger P_{n+1}, \quad \text{where } (Q_n, P_n) = (I, W_n).$$

Let  $A = (a_{ij})_{i,j=1}^s$  and  $b = (b_i)_{i=1}^s$  of a symplectic Runge–Kutta method,

$$W_{n+1} = W_n + h \sum_{i=1}^s b_i [f(\tilde{W}_i), \tilde{W}_i], \quad \tilde{W}_i = W_n + h \sum_{j=1}^s a_{ij} (X_j + Y_j + K_{ij}),$$

$$X_i = -(W_n + h \sum_{j=1}^s a_{ij} X_j) f(\tilde{W}_i), \quad Y_i = f(\tilde{W}_i) (W_n + h \sum_{j=1}^s a_{ij} Y_j),$$

$$K_{ij} = h \sum_{k=1}^s f(\tilde{W}_i) (a_{ik} X_k + a_{jk} K_{ik}),$$

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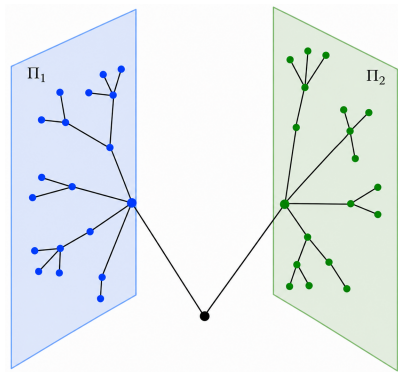
$$\begin{aligned} W_{n+1} &= W_n + h \sum_{i=1}^s b_i [f(\tilde{W}_i), \tilde{W}_i], & \tilde{W}_i &= W_n + h \sum_{j=1}^s a_{ij} (X_j + Y_j + K_{ij}), \\ X_i &= -(W_n + h \sum_{j=1}^s a_{ij} X_j) f(\tilde{W}_i), & Y_i &= f(\tilde{W}_i) (W_n + h \sum_{j=1}^s a_{ij} Y_j), \\ K_{ij} &= h \sum_{k=1}^s f(\tilde{W}_i) (a_{ik} X_k + a_{jk} K_{ik}), \end{aligned} \tag{2}$$

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## Part 2

# Biplanar Butcher series



## Runge–Kutta methods

Consider the following ODE where  $f : \mathbb{R}^d \rightarrow \mathbb{R}^d$  is a smooth vector field:

$$\dot{y}(t) = f(y(t)), \quad y(0) = y_0 \in \mathbb{R}^d.$$

A widely used class of integrators is the Runge–Kutta family

$$Y_i = y_0 + h \sum_{j=1}^s a_{ij} f(Y_j),$$

with

$$y_1 = y_0 + h \sum_{i=1}^s b_i f(Y_i),$$

$c_1$	$a_{11}$	$\cdots$	$a_{1s}$
$\vdots$	$\vdots$	$\ddots$	$\vdots$
$c_s$	$a_{s1}$	$\cdots$	$a_{ss}$
	$b_1$	$\cdots$	$b_s$

We can Taylor expand  $y_1$  around  $y_0$  to obtain

$$y_1 = y_0 + h \sum_{i=1}^s b_i \cdot f(y_0) + h^2 \sum_{i=1}^s b_i c_i \cdot f'(y_0) f(y_0) + \cdots.$$

Runge–Kutta method is *symplectic* if

$$b_i a_{ij} + b_j a_{ji} = b_i b_j, \quad \text{for } i, j = 1, \dots, s.$$

## Butcher series<sup>5,6</sup>

Consider rooted non-planar trees  $T := \{\bullet, \begin{smallmatrix} \bullet \\ \bullet \end{smallmatrix}, \begin{smallmatrix} \bullet & \bullet \\ \bullet & \bullet \end{smallmatrix}, \begin{smallmatrix} \bullet \\ \bullet \\ \bullet \end{smallmatrix}, \dots\}$ .

$$a_{RK}(\bullet) = \sum b_i, \quad a_{RK}\left(\begin{smallmatrix} \bullet \\ \bullet \end{smallmatrix}\right) = \sum b_i a_{ij} c_j,$$

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Let  $a : T \rightarrow \mathbb{R}$ , then a **Butcher series** is a formal sum  $B(a) : \mathbb{R}^d \rightarrow \mathbb{R}^d$ :

$$B_f(a)(y_0) := y_0 + ha(\bullet)f(y_0) + h^2 a\left(\begin{smallmatrix} \bullet \\ \bullet \end{smallmatrix}\right) f' f(y_0) + \\ h^3 \frac{a\left(\begin{smallmatrix} \bullet & \bullet \\ \bullet & \bullet \end{smallmatrix}\right)}{2} f''(f, f)(y_0) + h^3 a\left(\begin{smallmatrix} \bullet \\ \bullet \\ \bullet \end{smallmatrix}\right) f' f' f(y_0) + \dots.$$

RK methods:  $y_1 = B_f(a_{RK})(y_0),$

Order conditions:

Exact solution:  $y(h) = B_f(e)(y_0),$

$$a_{RK}(\tau) = e(\tau).$$

<sup>5</sup>J. C. Butcher. Coefficients for the study of Runge-Kutta integration processes. J. Austral. Math. Soc., 3:185–201, 1963.

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# Biplanar forests

Start with the following recursive definition:

- 1 a *biplanar tree* is denoted by  $B^+(\pi, \eta)$  where  $(\pi, \eta)$  is a biplanar forest,
- 2 a *biplanar forest*  $(\pi, \eta)$  is a pair of ordered monomials  $\pi$  and  $\eta$  of biplanar trees.

The set of trees is denoted by  $BT$ , ordered monomials of trees by  $T(BT)$  and the set of forests by  $BF$ . Note that  $(\pi, \eta) = (\eta, \pi)$ .

Let the *Butcher product* for  $\tau \in T$  and  $\pi \in F$  be defined as

$$\tau \triangleright B^+(\pi) = B^+(\tau\pi).$$

The *forest momentum map*  $\psi : BF \rightarrow T^2$  is given by

$$\psi(\pi, \eta) = \psi(\pi)\psi(\eta), \quad \psi(\pi \cdot \tau) = \psi(\pi) \triangleright \psi(\tau),$$

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## Biplanar action

Let  $\mathcal{U}^2$  be the commutative product of the universal enveloping algebra of  $\mathfrak{u}(d)$ , that is,  $\mathcal{U}^2 := \mathcal{U} \cdot \mathcal{U}$  with  $(A, B) = (B, A)$  where  $A, B \in \mathcal{U}$ .

Consider the action  $\odot : \mathcal{U}^2 \otimes \mathfrak{u}(d) \rightarrow \mathfrak{u}(d)$ ,

$$(A, B) \odot W = AWB^\dagger + BWA^\dagger,$$

which generalizes the well-known actions,

$$\text{Ad}_Q^* W = \frac{1}{2}(Q, Q) \odot W, \quad \text{ad}_{\tilde{W}}^* W = (\tilde{W}, I) \odot W.$$

Elementary differential  $\mathbb{F}_f(\pi, \eta)$  is defined as,

$$\begin{aligned}\mathbb{F}_f(\pi, \eta) \odot W &= (\mathbb{F}_f(\pi)(W), \mathbb{F}_f(\eta)(W)) \odot W, \\ \mathbb{F}_f(\pi \cdot \eta)(W) &= \mathbb{F}_f(\eta)(W) \cdot \mathbb{F}_f(\pi)(W), \\ \mathbb{F}_f(B^+(\pi, \eta))(W) &= f(\mathbb{F}_f(\pi, \eta) \odot W).\end{aligned}$$

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## Biplanar action

Let  $\mathcal{U}^2$  be the commutative product of the universal enveloping algebra of  $\mathfrak{u}(d)$ , that is,  $\mathcal{U}^2 := \mathcal{U} \cdot \mathcal{U}$  with  $(A, B) = (B, A)$  where  $A, B \in \mathcal{U}$ .

Consider the action  $\odot : \mathcal{U}^2 \otimes \mathfrak{u}(d) \rightarrow \mathfrak{u}(d)$ ,

$$(A, B) \odot W = AWB^\dagger + BWA^\dagger,$$

which generalizes the well-known actions,

$$\text{Ad}_Q^* W = \frac{1}{2}(Q, Q) \odot W, \quad \text{ad}_{\tilde{W}}^* W = (\tilde{W}, I) \odot W.$$

Elementary differential  $\mathbb{F}_f(\pi, \eta)$  is defined as,

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## Biplanar Butcher series

Biplanar Butcher series are defined for  $\alpha : BF \rightarrow \mathbb{R}$  as

$$B_f(\alpha) = \sum_{(\pi, \eta) \in BF} \frac{\alpha(\pi, \eta)}{\sigma(\pi, \eta)} \mathbb{F}_f(\pi, \eta).$$

### Theorem (Lie–Poisson reduction of biplanar Butcher series)

Let  $a, b : F \rightarrow \mathbb{R}$  be such that  $a(\mathbf{1}) = 1$ ,  $a(\pi \cdot \eta) = a(\pi)a(\eta)$  and  $b(\mathbf{1}) = 0$ ,  $b(\pi \cdot \eta) = 0$ . Then,

$$\mu \circ B_{\mu_{\sharp} f}(a) = B_f(a \circ \psi) \circ \mu, \quad B_{\mu_{\sharp} f}(b) = \mu_{\sharp} B_f(b \circ \psi),$$

The composition and substitution laws follow,

$$B_f(a_1 \circ \psi) \circ B_f(a_2 \circ \psi) = B_f((a_2 * a_1) \circ \psi),$$
$$B_{\frac{1}{h} B_f(b \circ \psi)}(a \circ \psi) = B_f((b \star a) \circ \psi).$$

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Let  $\alpha : BF \rightarrow \mathbb{R}$  be a coefficient map and let  $\alpha_T := \alpha|_{T(BT)}$ .

### Corollary (Butcher series of ISOSYRK methods)

Let  $\Phi_h$  be a symplectic Runge–Kutta method which can be expanded as  $B_{\mu_{\sharp}f}(a)$  and let  $\Psi_h$  be the corresponding ISOSYRK method, then,

$$\Psi_h(W_0) = B_f(\alpha) \odot W_0 = Ad_{B_f(\alpha_T)(W_0)}^* W_0,$$

where  $\alpha = a \circ \psi$  and  $B_f(\alpha_T)(W_0) \in U(d)$ .

### Corollary (Backward error analysis of ISOSYRK methods)

Let  $\Phi_h$  be a symplectic Runge–Kutta method with the modified equation given by  $B_{\mu_{\sharp}f}(b)$ , then,  $B_f(\beta)$  is the modified vector field of the corresponding ISOSYRK method  $\Psi_h$  with  $\beta = b \circ \psi$ . Moreover,

$$B_f(\beta) \odot W_0 = ad_{B_f(\beta_T)(W_0)}^* W_0,$$

where  $B_f(\beta_T)(W_0) \in \mathfrak{u}(d)$ .

Moreover, the modified Hamiltonians are related by  $\tilde{H} = \tilde{\mathcal{H}} \circ \mu$ .

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Let us use the following notation,

$$\epsilon = \frac{h}{\hbar}, \quad \delta = f(W), \quad \gamma = \delta^2 + f([\delta, W]).$$

Modified Hamiltonian of the midpoint ISOSYRK method is given by

$$\begin{aligned} \tilde{H}_h(W) = & H(W) - \frac{1}{12}\epsilon^2 \langle \delta W \delta^\dagger, \delta \rangle_d - \frac{1}{24}\epsilon^2 \langle [\delta, W], f([\delta, W]) \rangle_d \\ & + \frac{1}{80}\epsilon^4 \langle \gamma W \gamma^\dagger, \delta \rangle_d \\ & + \frac{1}{160}\epsilon^4 \langle \gamma W + W \gamma^\dagger, f(\gamma W + W \gamma^\dagger) \rangle_d \\ & + \frac{1}{240}\epsilon^4 \langle \gamma W \delta^\dagger + \delta W \gamma^\dagger, f([\delta, W]) \rangle_d \\ & + \frac{1}{240}\epsilon^4 \langle \gamma W + W \gamma^\dagger, f(\delta W \delta^\dagger) \rangle_d \\ & + \frac{7}{480}\epsilon^4 \langle \delta W \delta^\dagger, f(\delta W \delta^\dagger) \rangle_d + \mathcal{O}(\epsilon^6). \end{aligned}$$

Engø-Faltinsen<sup>7</sup> introduce Runge–Kutta–Munthe-Kaas methods for Lie–Poisson systems. A Lie–Poisson system can be written as,

$$W(t) = \text{Ad}_{\exp(\omega(t))}^* W_0, \quad \text{where } \dot{\omega} = \text{dexp}_{\omega}^{-1} f(W(t)).$$

Therefore, given any Runge–Kutta method  $\Phi_h$ , it can be integrated as

$$W_1 = \text{Ad}_{\exp(\Phi_h(\omega_0))}^* W_0, \quad \text{where } \omega_0 = 0.$$

### Proposition

*RKMK methods are expanded as biplanar Butcher series with coefficient maps  $\alpha : BF \rightarrow \mathbb{R}$  satisfying  $\alpha_T(\pi \sqcup \eta) = \alpha_T(\pi)\alpha_T(\eta)$ .*

### Corollary

*ISOSYRK methods are not RKMK methods.*

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<sup>7</sup>K. Engø and S. Faltinsen, Numerical Integration of Lie–Poisson Systems While Preserving Coadjoint Orbits and Energy, *SIAM Journal on Numerical Analysis*, 39 (2001)

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# Conclusion

In this talk, we have,

- 1 introduced biplanar forest and Butcher series,
- 2 introduced forest momentum map and performed Lie–Poisson reduction of Butcher series,
- 3 obtained composition and substitution laws for biplanar Butcher series,
- 4 analysed geometric properties of ISOSYRK methods,
- 5 compared ISOSYRK methods with RKMK methods for Lie–Poisson systems.

Thank you for your attention!

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