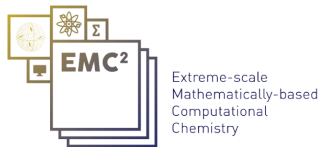


Parareal algorithm for stochastic differential equations

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Stochastic differential equation

We consider the following overdamped Langevin equation:

$$dX_t = b(X_t) dt + \sigma(X_t) dW_t \quad \text{for all } t \in [0, T]$$

with a given drift b , diffusion σ and a Brownian motion W_t .

Numerical scheme: Euler Maruyama

$$X_{n+1}^F = X_n^F + \Delta t b(X_n^F) + \sqrt{\Delta t} \sigma(X_n^F) G_{n+1}$$

- $G_n \sim \mathcal{N}(0, 1)$
- We assume that b and/or σ have a high computation cost
- We use coarse drift and diffusion

$$X_{n+1}^C = X_n^C + \Delta t b_C(X_n^C) + \sqrt{\Delta t} \sigma_C(X_n^C) G_{n+1},$$

How can this rough model be used to calculate the fine solution?

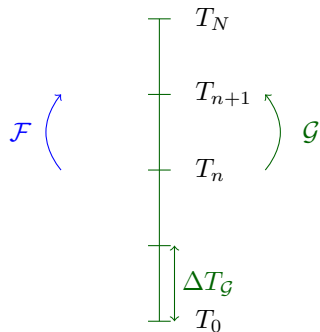
Parareal for ODEs

→ J. L. Lions, Y. Maday, G. Turinici,
Résolution d'EDP par un schéma en temps "Pararéel", 2001

We have two propagators:

- **Coarse** propagator $\mathcal{G}(\mathcal{T}_n, M)$
Roughly solves the equation on \mathcal{T}_n with initial condition M
→ **cheap**
→ performed **sequentially**
 - **Fine** propagator $\mathcal{F}(\mathcal{T}_n, M)$
Precisely solves the equation on \mathcal{T}_n with initial condition M
→ performed **in parallel**
- Correction step :

$$X_{n+1}^{k+1} = \underbrace{\mathcal{F}(\mathcal{T}_n, X_n^k)}_{\text{in parallel}} + \mathcal{G}(\mathcal{T}_n, X_n^{k+1}) - \mathcal{G}(\mathcal{T}_n, X_n^k)$$



Studied quantity

- Parareal for trajectories?

→ We are interested in the mean value of a given function ψ

- $\psi(X)$: position at final time
- $\psi(X)$: time to cross a potential barrier

$$\mathbb{E}(\Psi(X)) \quad ?$$

Importance sampling

- Monte-Carlo
 - **Important Sampling** : $\mathbb{E}(\psi(X)) = \mathbb{E}(\psi(Y)w(Y))$
 - w is a weight function which illustrates how the distribution of Y relates to the distribution of X
 - Instead of simulating X , we simulate Y , e.g. if Y is easier to compute
-
- $X = X^F, Y = X^k$

$$\mathbb{E}(\psi(X^F)) = \mathbb{E}(\psi(Y^k)w(Y^k))$$

Importance sampling for Parareal

Theorem

If $k \geq 0$, we have an explicit formula for w (here for $\sigma = \sigma_C$):

$$\mathbb{E}(\psi(X^F)) = \mathbb{E}(\psi(X^k) \exp(-(\|\mathcal{G}_N^k\|^2 - \|\mathbf{G}_N\|^2)/2))$$

with

$$\mathcal{G}_N^k = (\mathcal{S}^F)^{-1}(X^k)$$

- Calculation of \mathcal{G}_N^k imply the inversion $(\mathcal{S}^F)^{-1}$ but can be performed in parallel

→ We can correct the error from parareal which is now exact!

Some remarks. . .

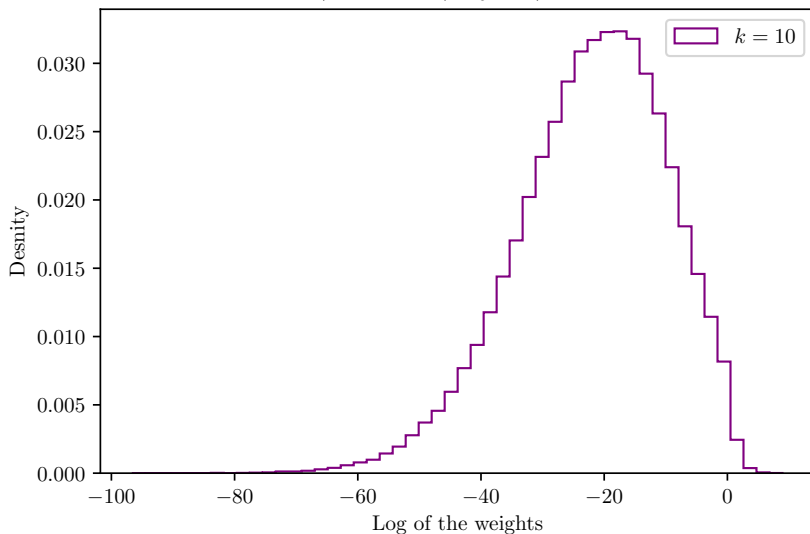
$$\mathbb{E}(\psi(X^F)) = \mathbb{E}(\psi(Y^k)w(Y^k))$$

- The correction formula is true for all k
- If $k = 0$, we just replace the fine solver by a coarse solver
- Then what changes if k increases ?

→ We must **balance** between computation time (which increases with k) and the convergence rate of the Monte Carlo method (which decreases with k)

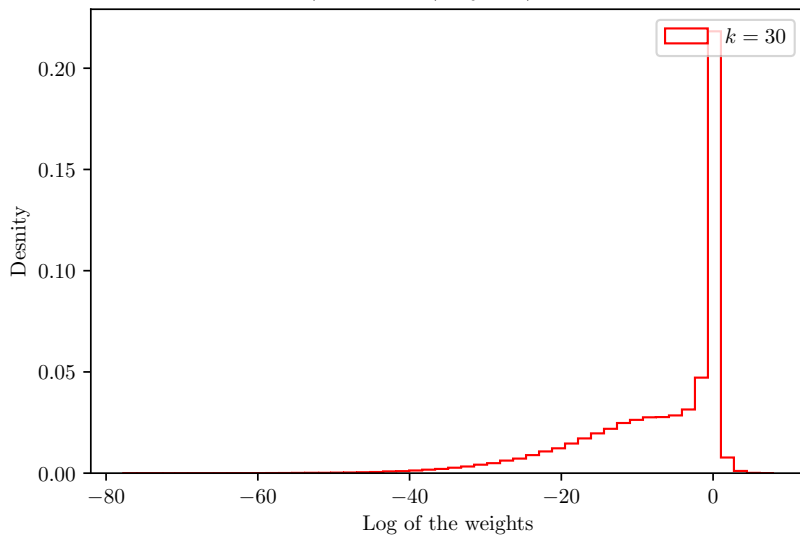
Weight distributions

$T = 50, N = 1000, X_0 = 1, I = 250000$

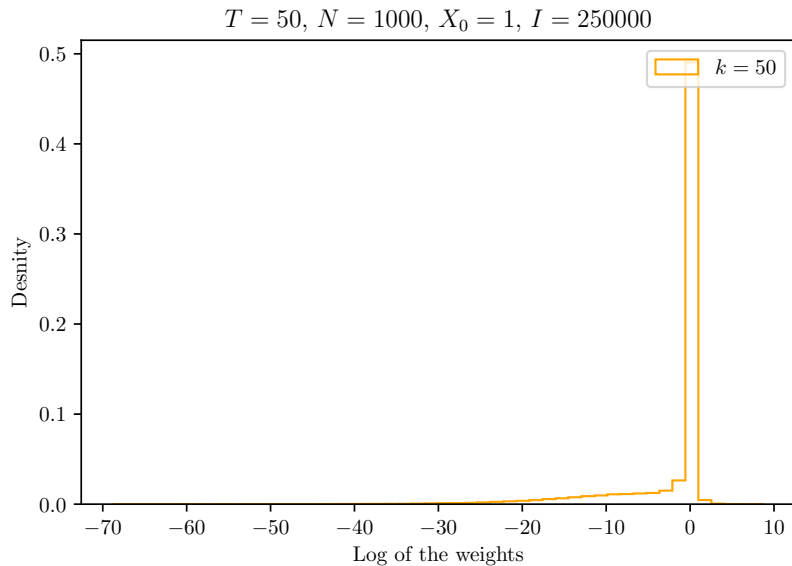


Weight distributions

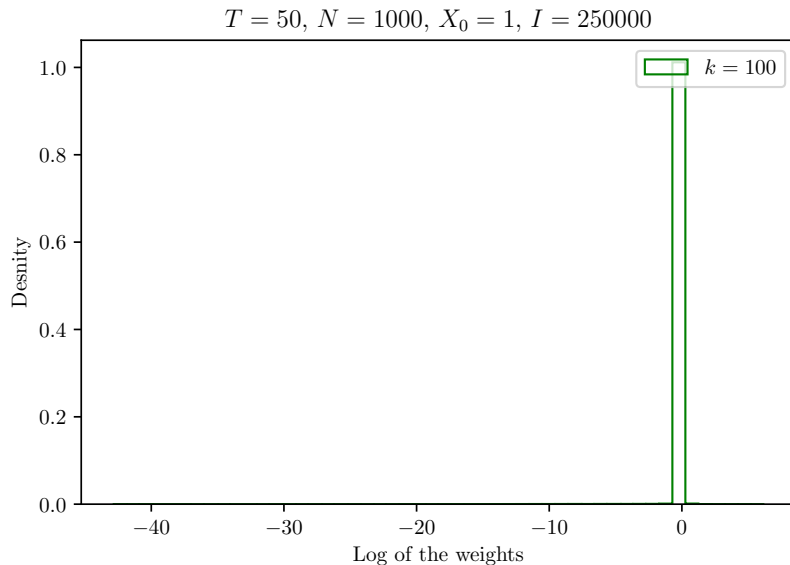
$T = 50, N = 1000, X_0 = 1, I = 250000$



Weight distributions



Weight distributions



Some remarks. . .

- Weight captures the difference between the fine solver and the coarse solver, with a mean value of 1
- But **high variance** (due to the exponential term?) \rightarrow It must be minimized as much as possible
- If k is large, $w \sim 1$ and correction is useless

Stopping time

$$w = w_1 w_2 \dots w_N$$

with

$$w_i = \exp\left(-\frac{\mathcal{G}_i^2(G_1, \dots, G_i) - G_i^2}{2}\right)$$

- The larger N is, the more random terms there are
- If the studied phenomenon is the transition from one well to another, which occurs after 100 time steps, we would need to consider weights $w_1 w_2 \dots w_{100}$ and not up to N

Stopping time

Theorem

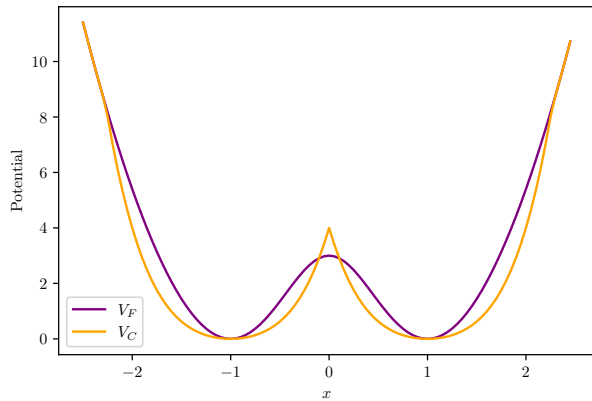
Let $k \in \llbracket 0, K \rrbracket$. If there exists a stopping time N_k^* such that $\Psi(x_1, \dots, x_N) = \Psi(x_1, \dots, x_{N^*})$ with $N^* \leq N$, then, we have

$$\mathbb{E}(\Psi(X^F)) = \mathbb{E}\left(\Psi(X_{N_k^*}^k)w(X_{N_k^*}^k)\right),$$

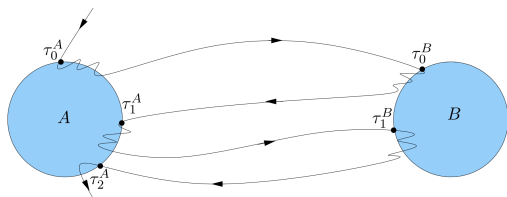
where $X_{N_k^*}^k$ denotes the vector of the N_k^* first elements of X^k .

→ We reduce the length of the trajectories included in the weights, and we avoid the uncertainty caused by large times

1D test case : Potential curve



Hill formula

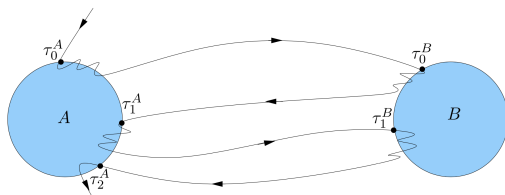


$$T_{AB} = \tau_A \left(\frac{1}{\mathbb{P}_B} - 1 \right) + \tau_B$$

with

- T_{AB} : time from A to B
- τ_A : time from A to A without B
- τ_B : time from A to B without A
- \mathbb{P}_B : probability of B from A

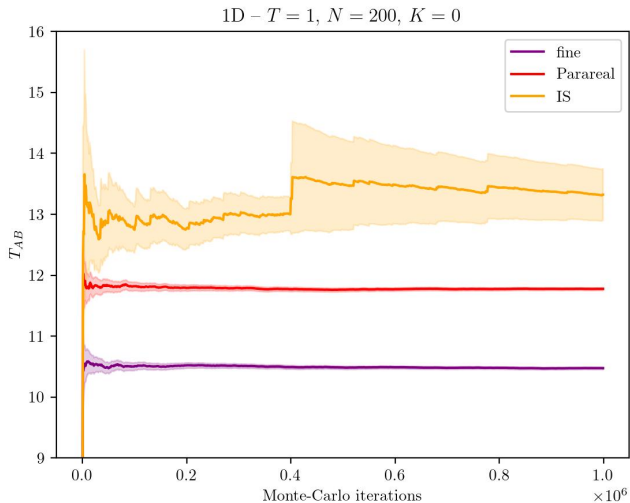
Hill formula



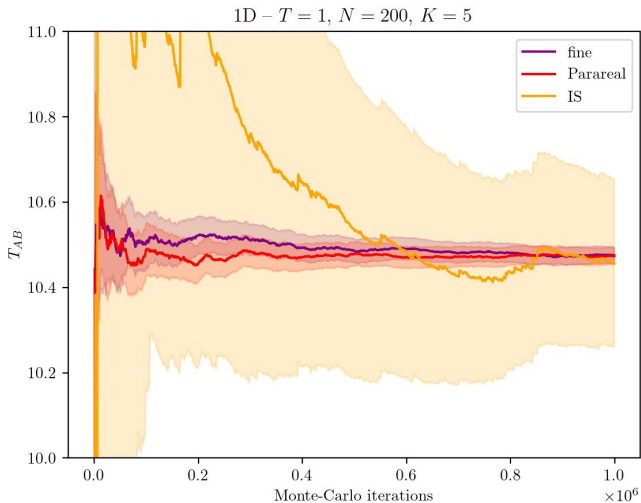
$$T_{AB} = \tau_A \left(\frac{1}{\mathbb{P}_B} - 1 \right) + \tau_B$$

- Only short trajectories : A to B and A to A is fast : **N can be small**
- It doesn't save time in the simulation, but it greatly reduces the length of the trajectories, so parallel is more efficient
- This greatly reduces the variance in the weights

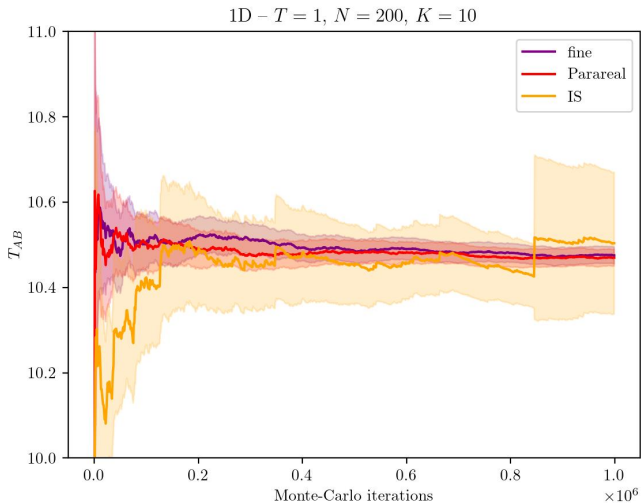
1D test case : Monte-Carlo convergence



1D test case : Monte-Carlo convergence



1D test case : Monte-Carlo convergence



Conclusion & perspectives

- Parareal for stochastic trajectories
 - Importance sampling for error correction: calculation of weights
 - Random stopping time: weights are considered only at this time step
 - Reducing the length of trajectories using Hill formula
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- Unsatisfactory numerical results: it is difficult to find cases where parareal performs poorly but IS is more effective in a small number of simulations
 - Confidence interval with IS

Conclusion & perspectives

- Parareal for stochastic trajectories
- Importance sampling for error correction: calculation of weights
- Random stopping time: weights are considered only at this time step
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- Unsatisfactory numerical results: it is difficult to find cases where parareal performs poorly but IS is more effective in a small number of simulations
- Confidence interval with IS

- Should we use weights or IS as an indicator of convergence?
- Situations that are less favorable to parareal? For example, by increasing the importance of brownian motion

Thank you for your attention!

