

VERTICAL MOTION OF A FLOATING CYLINDER IN THE BOUSSINESQ

REGIME

CANUM 2026

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IRMAR

SIM NS
FOUNDATION



Inria

1. Part I: Modelisation of the problem

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- Context & Notations
- Modelisation & reformulation of the problem

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2. Part II: A first scheme for the numerical simulations

- Discretization
- Energy inequalities

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- Spectral scheme
- Comparaison with the first method

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PART I:

Context & Notations

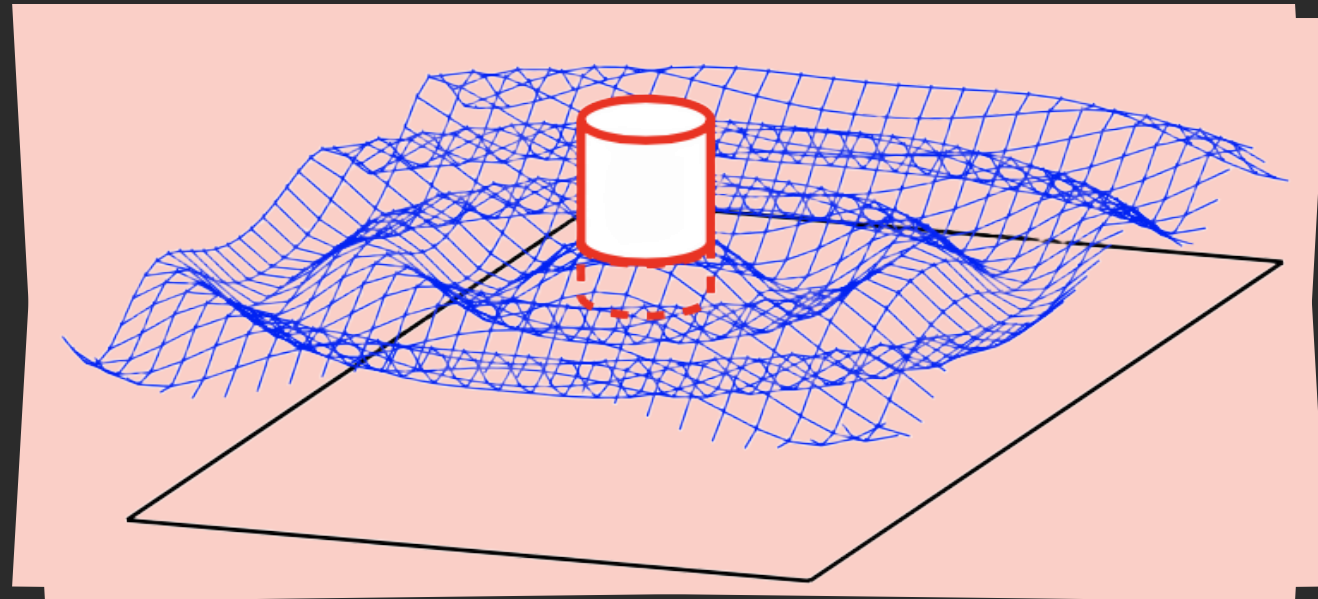


Figure - Freely floating cylinder

Context

PART I:

Context & Notations

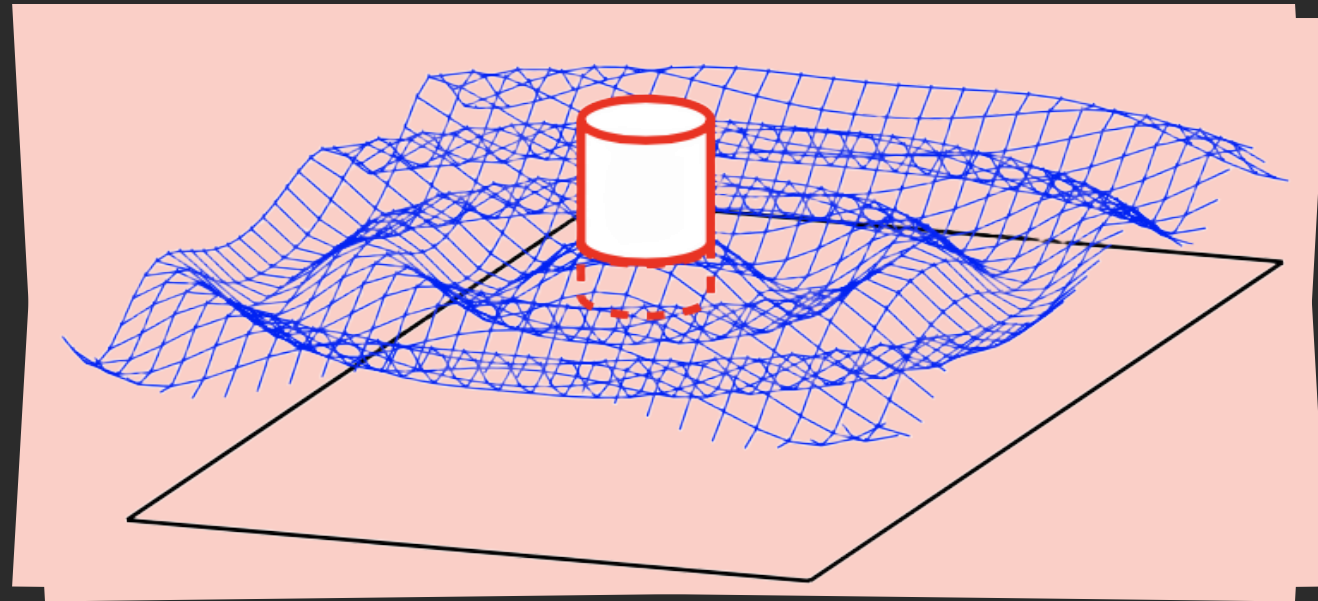


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- Cylinder of radius $R > 0$,

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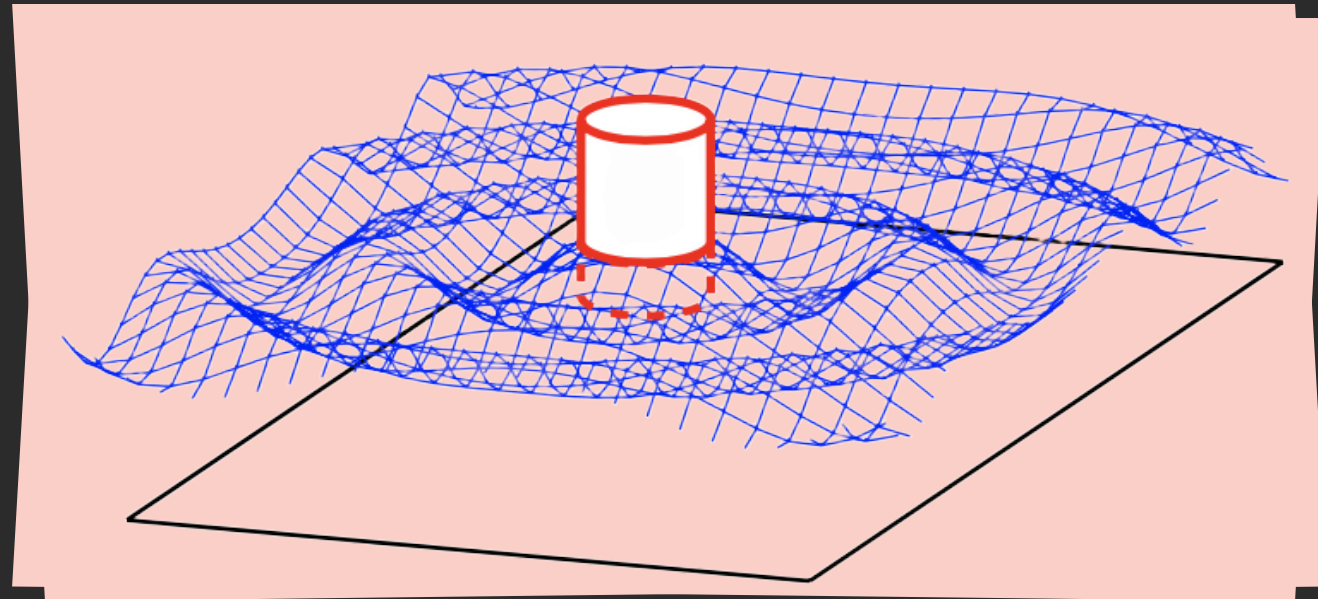


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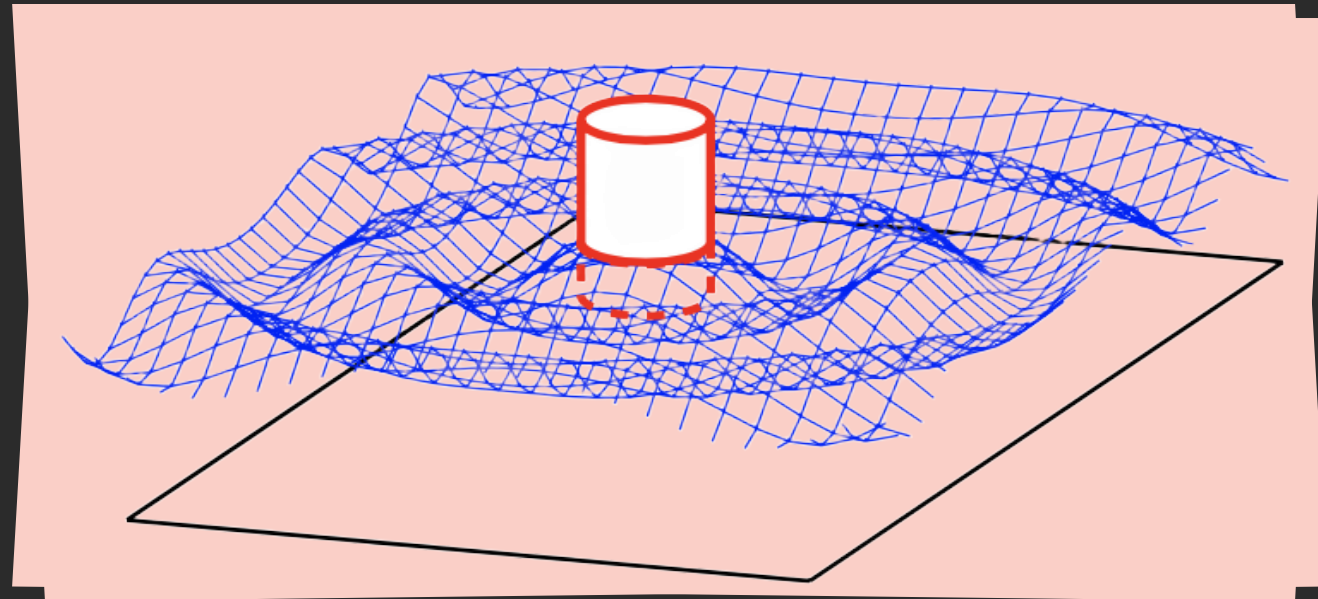


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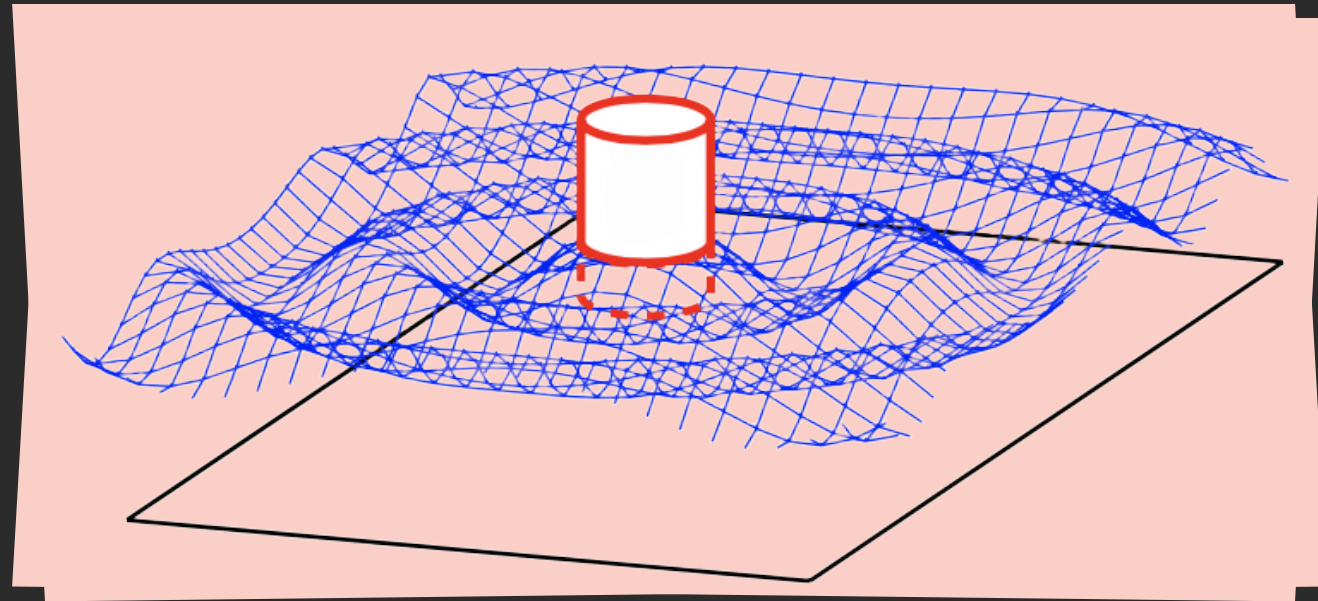


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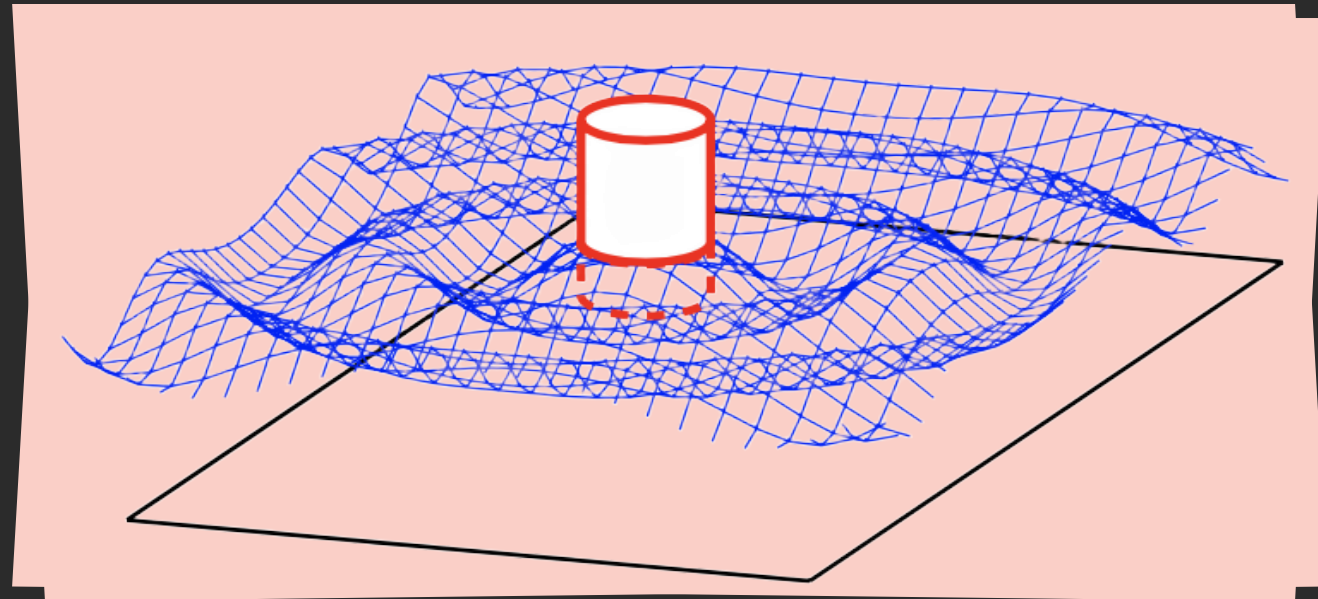


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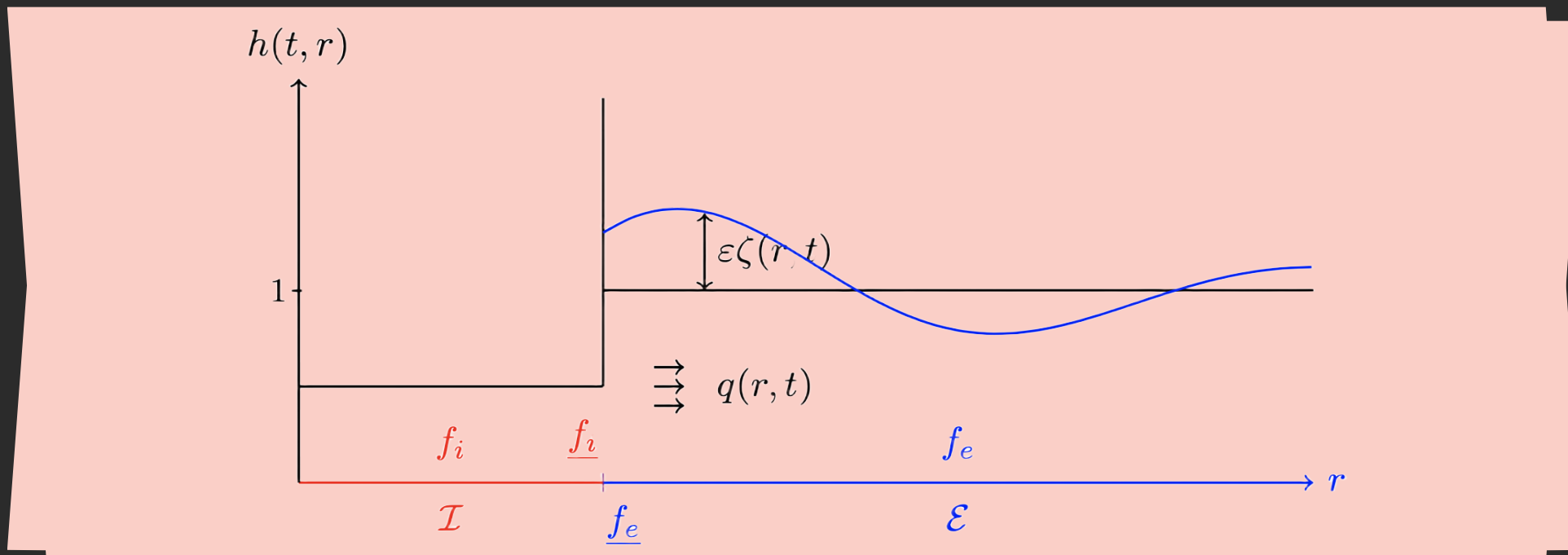


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- $\kappa = \frac{\text{typ. depth}}{\text{typ. horiz. scale}}$

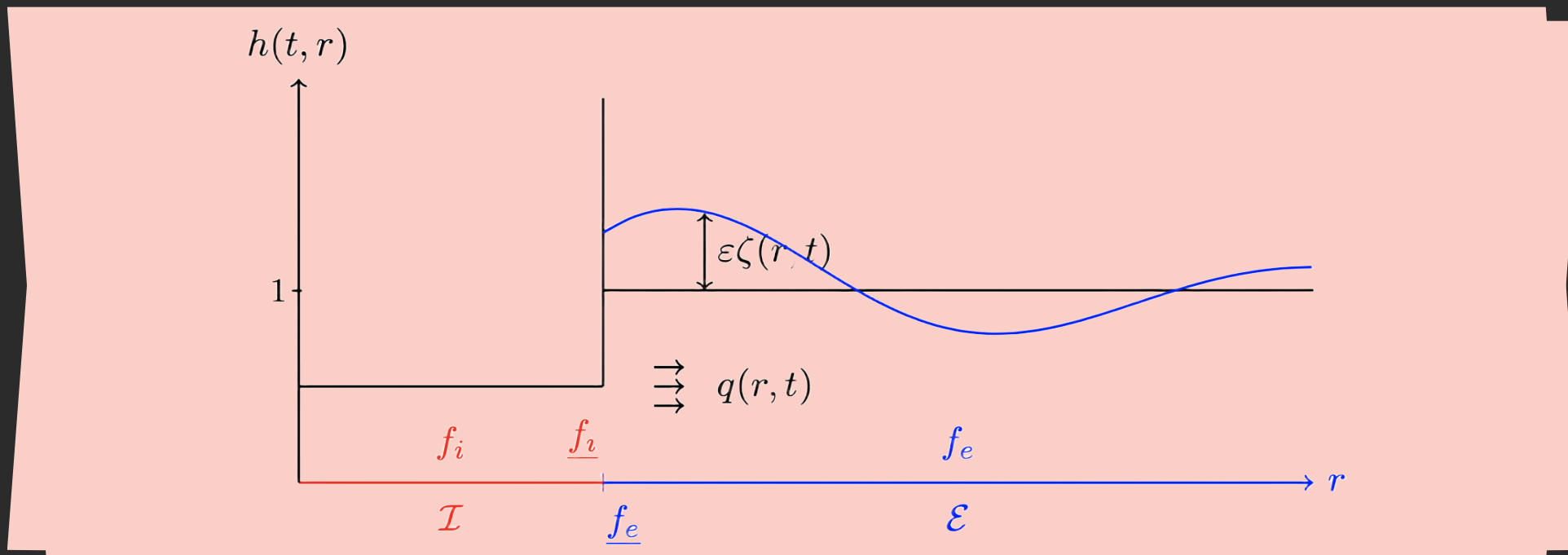


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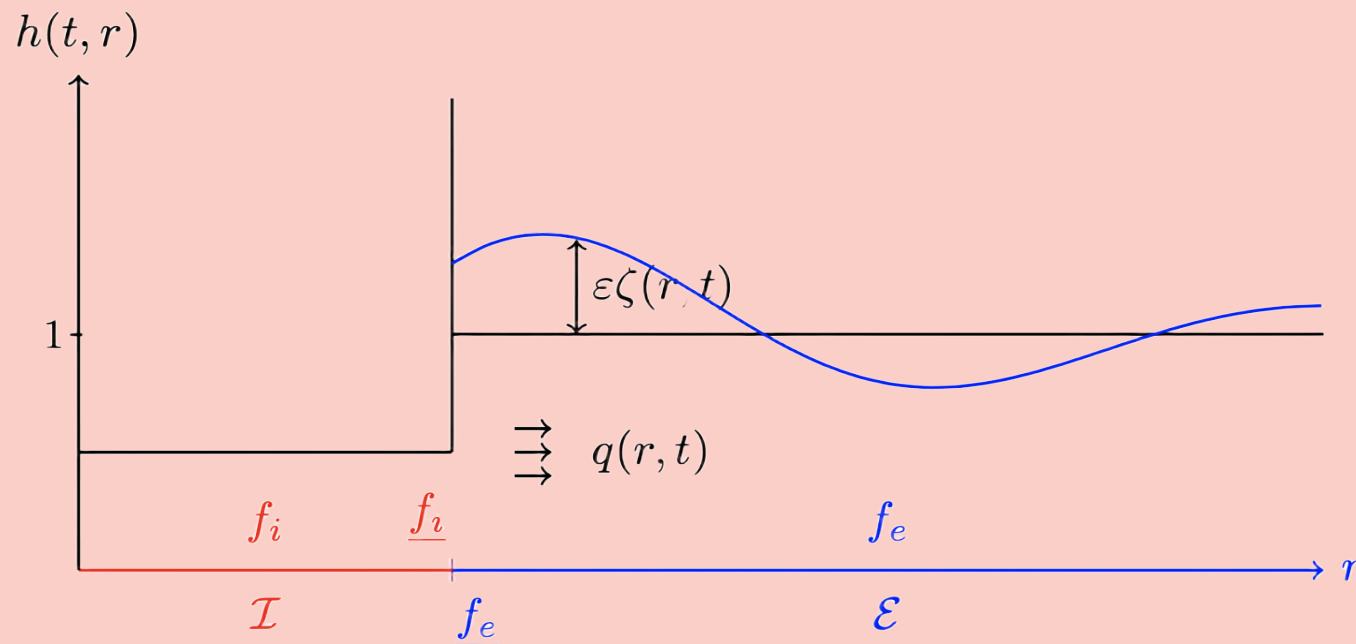


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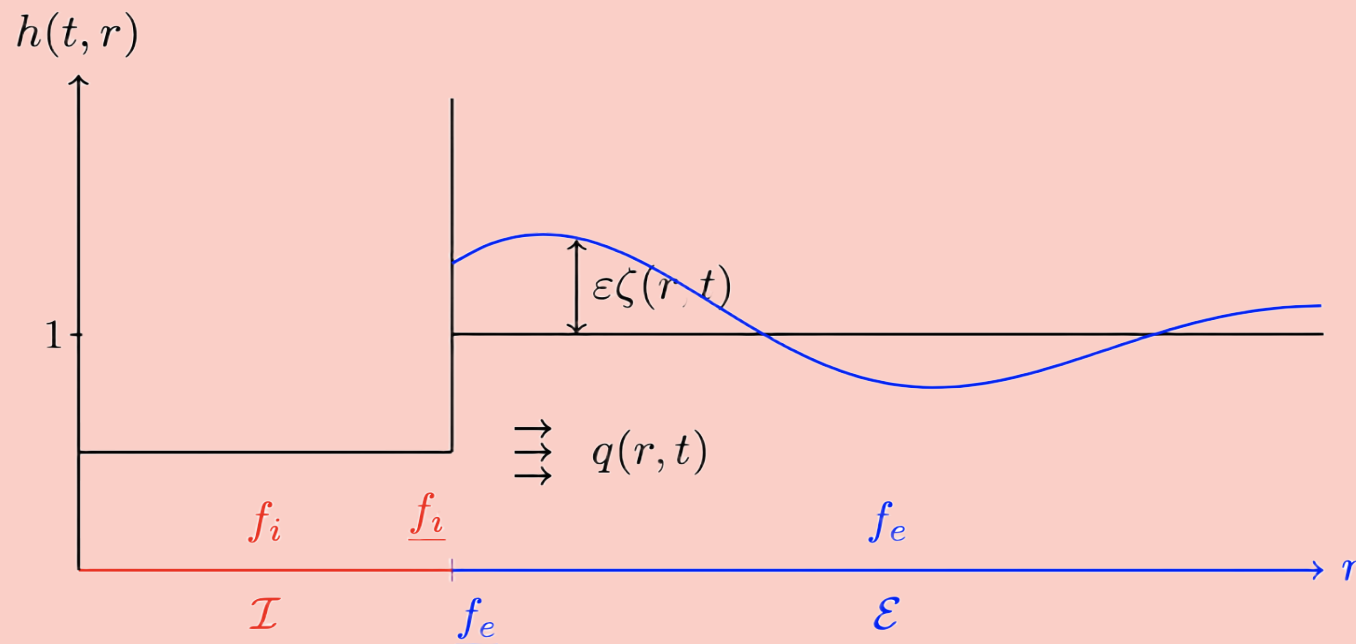


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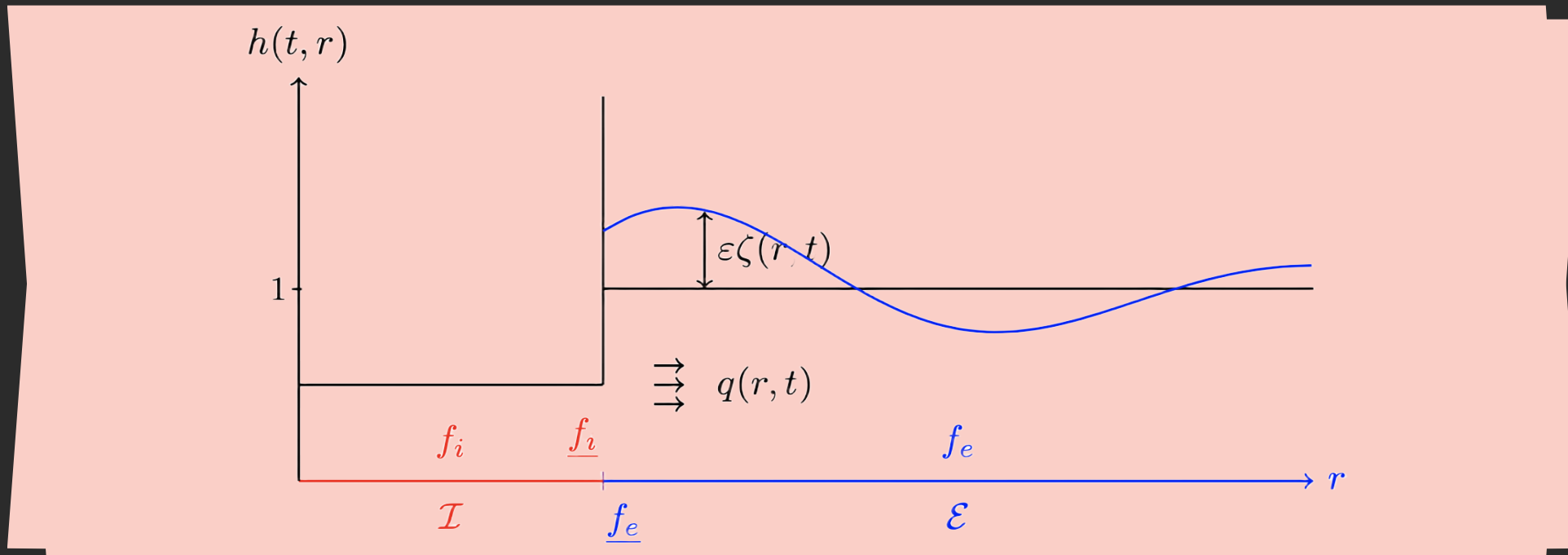


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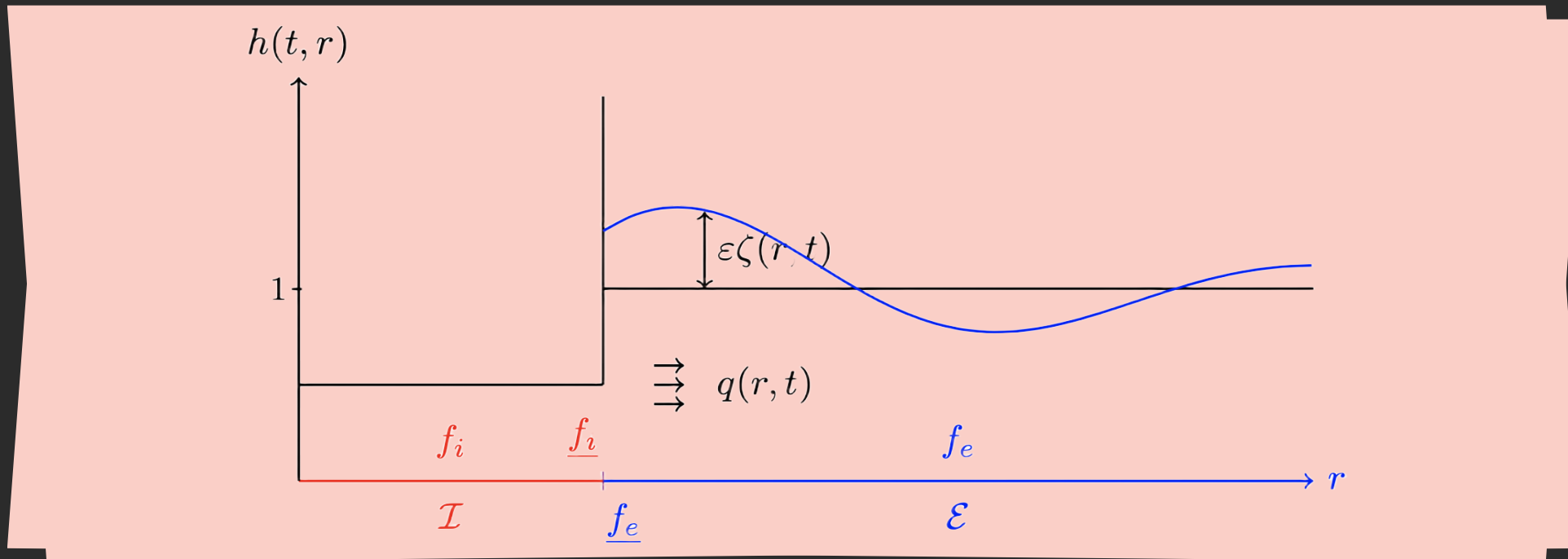


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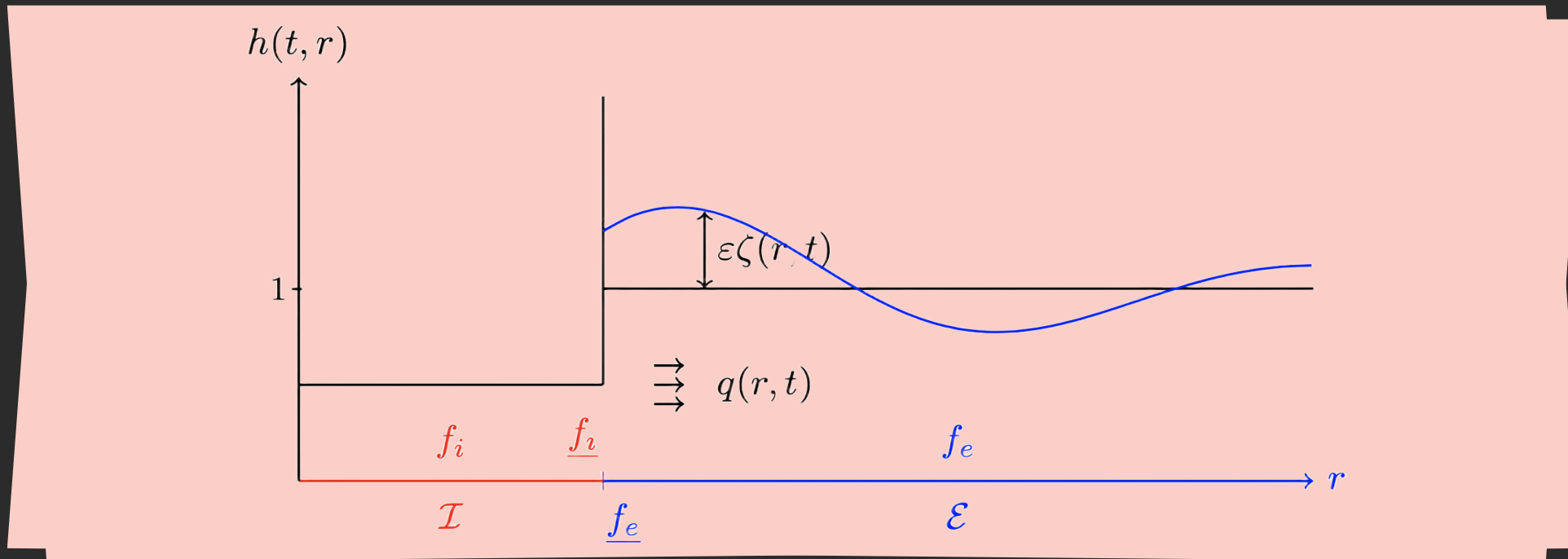


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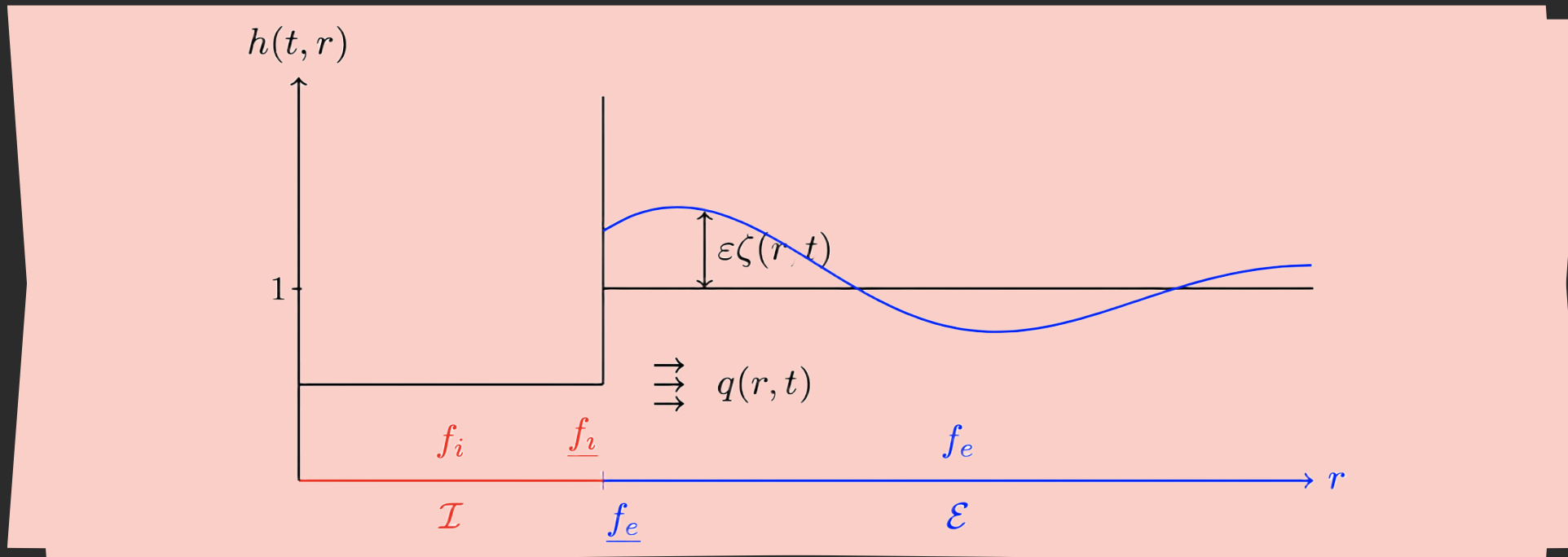


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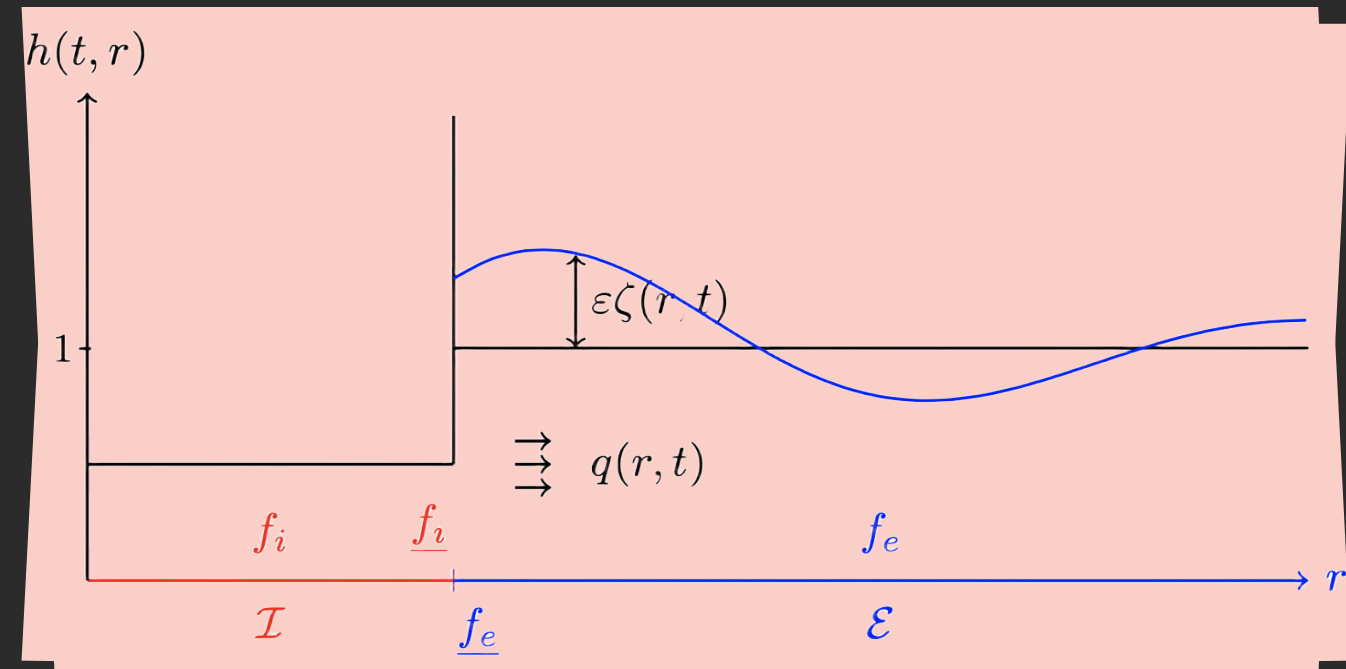
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Remarks:

- In \mathcal{I} , $\zeta_i = \delta$ and P_i is unknown
- In \mathcal{E} , $P_e = P_{\text{atm}}$ and ζ_e is unknown

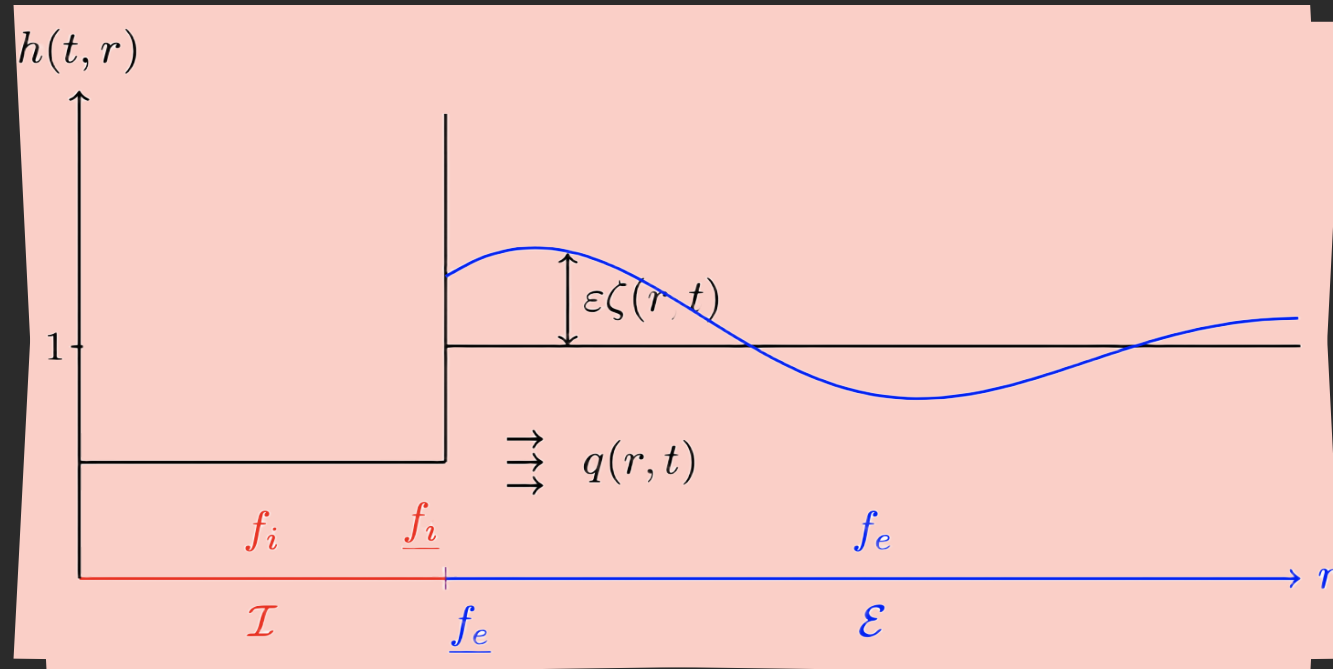
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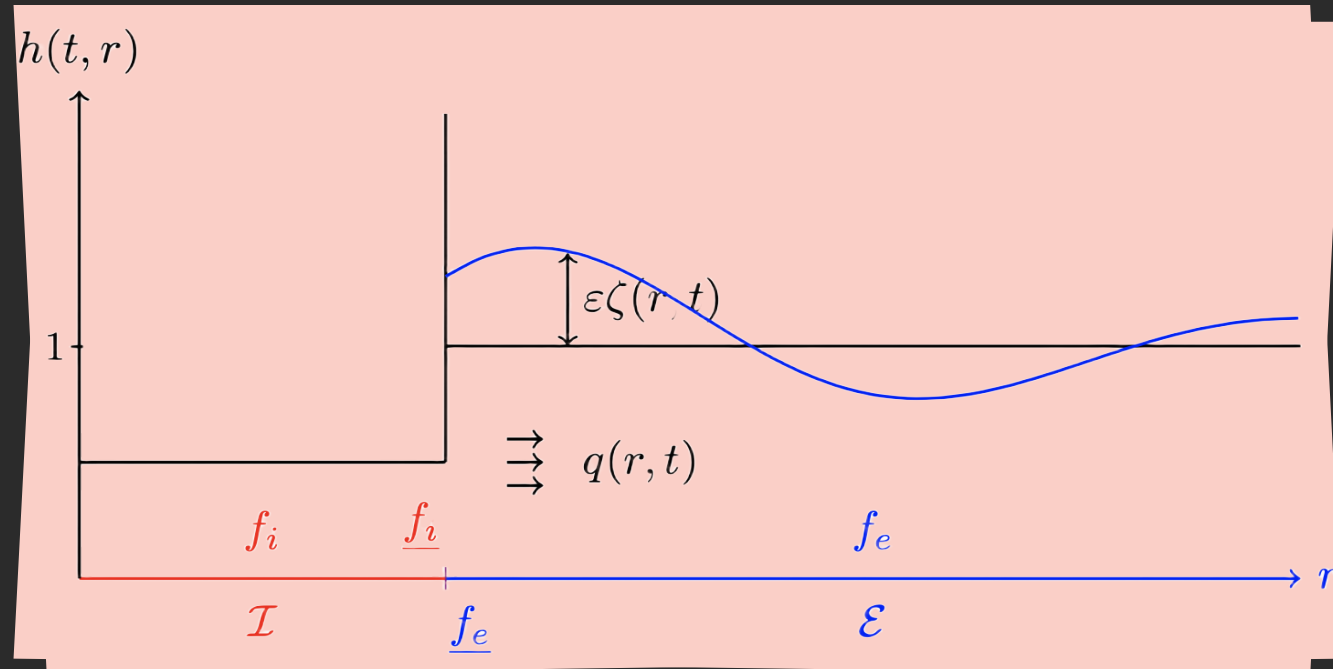


Boussinesq-Abbott equations:

$$\begin{cases} \partial_t \zeta + \operatorname{div} q = 0, \\ (1 - \kappa^2 \partial_r \mathbf{d}_r) \partial_t q + \partial_r \zeta = -\partial_r P, \\ \mathbf{d}_r = \partial_r + \frac{d-1}{r}. \end{cases}$$

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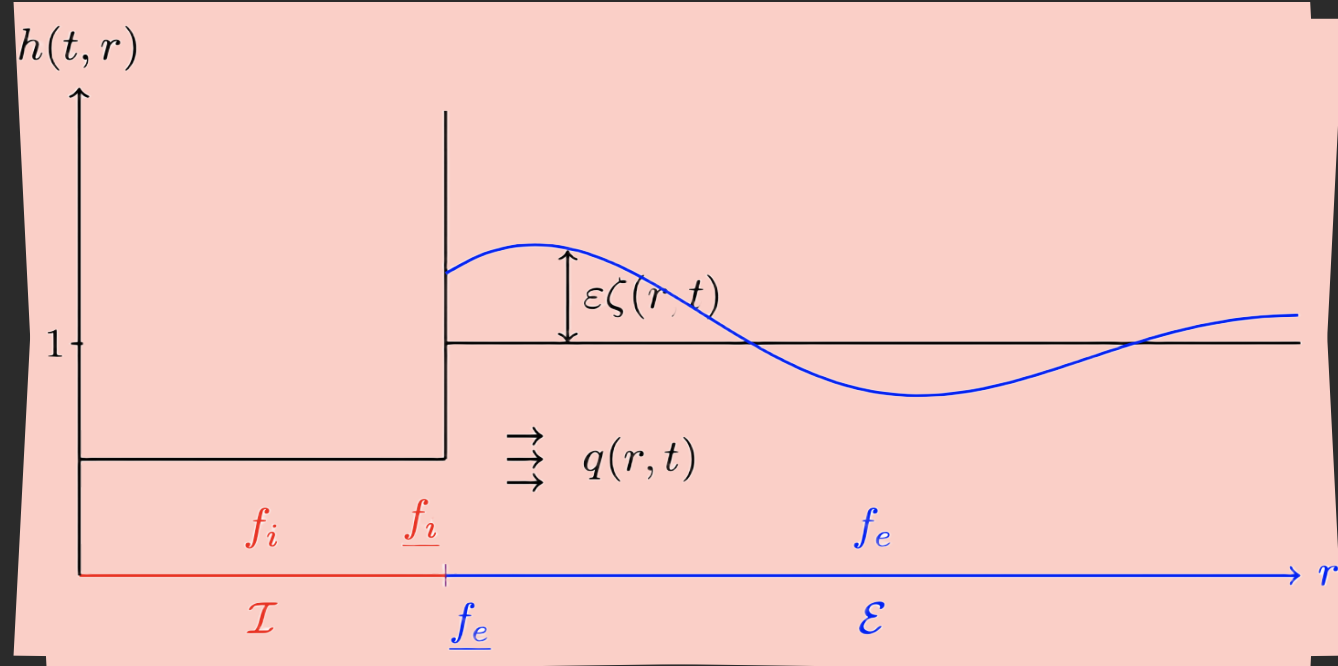
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Newton's equation:

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 - $\underline{f_e} = \lim_{\rho \rightarrow R} f(r + \rho)$

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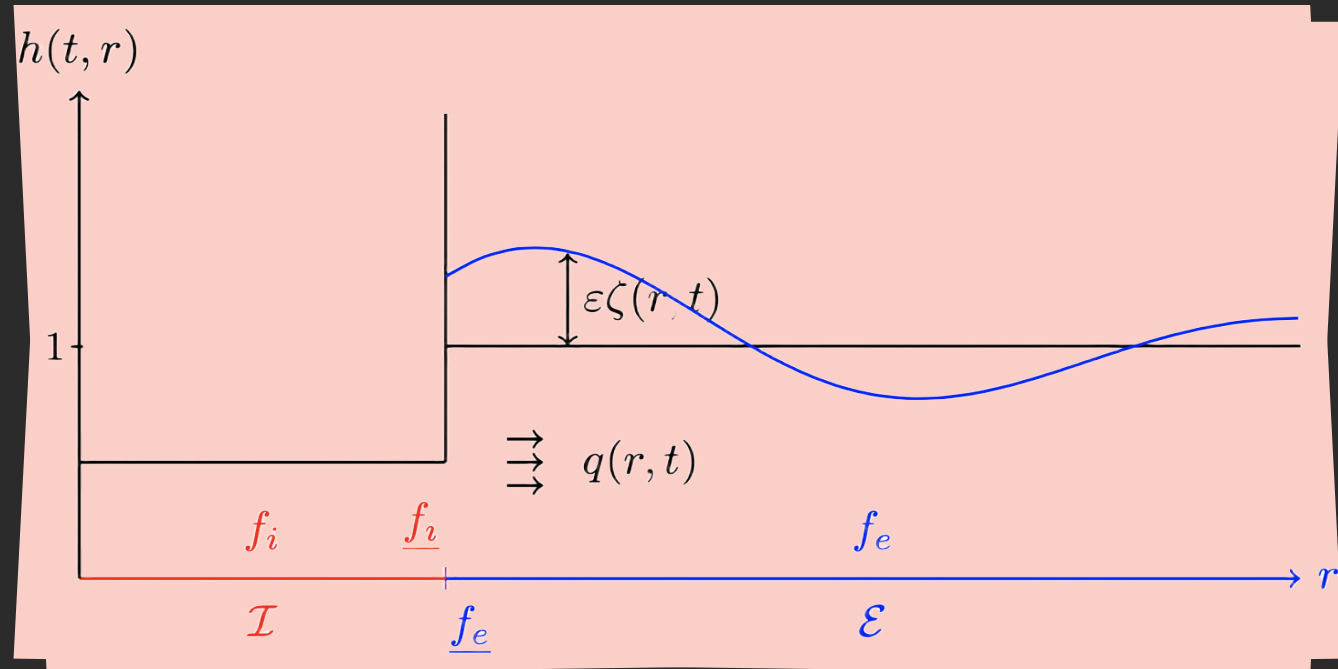
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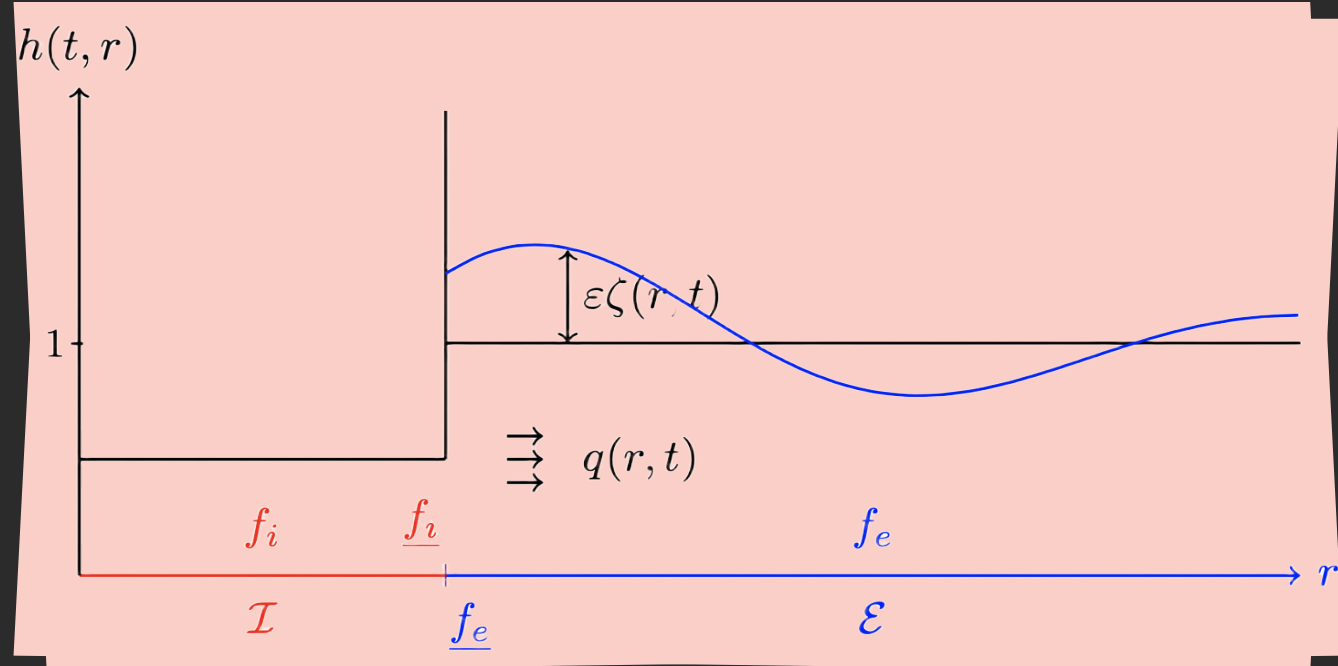
- Transmission conditions:

- $\underline{q_i} = \underline{q_e}$

- $\underline{P_i} = \mathcal{L}(\zeta, q, \delta)$

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 - $\underline{q_i} = \underline{q_e}$
 - $\underline{P_i} = \mathcal{L}(\zeta, q, \delta)$
- Remark:
 - Since $\dot{\zeta}_i = \dot{\delta}$, then $\underline{q_e} = -\frac{R}{2} \dot{\delta}$

PART I

Reformulation of the problem

THEOREM 1 Reformulation

PDE system on \mathbb{R}^+ + Transmission conditions

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$$\begin{cases} \partial_t \zeta + \partial_r q = -\frac{q}{r}, \\ \partial_t q + \partial_r \mathcal{R}\zeta = -\ddot{\delta} K(r/\kappa), \quad r > R, t > 0 \\ \underline{q} = -R\dot{\delta}, \end{cases} + \begin{cases} \kappa^2 \underline{\ddot{\zeta}} + \underline{\zeta} = \underline{\mathcal{R}\zeta} - G(R/\kappa)\ddot{\delta}, \\ \tilde{m}\ddot{\delta} + \delta = \kappa^2 \underline{\ddot{\zeta}} + \underline{\zeta}, \end{cases} \quad t > 0.$$

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$$\Rightarrow \begin{cases} \partial_t \zeta + \operatorname{div} q = 0, & r > R \\ \kappa^2 \ddot{\zeta} + \zeta = \mathfrak{R}_1 \zeta - \frac{R}{2} \ddot{\delta} G(r/\kappa), & r \geq R \\ \tilde{m} \ddot{\delta} + \delta = \kappa^2 \underline{\zeta} + \underline{\zeta}, \\ \underline{q} = -\frac{R}{2} \dot{\delta}. \end{cases}$$

THEORETICAL RESULTS

DEFINITION The space H_r^1

We define the space H_r^1 as the functional space on $(R, +\infty)$ equipped with the norm

$$\|\cdot\|_{H_r^1}^2 = \|\cdot\|_{L_r^2}^2 + \|\operatorname{div} \cdot\|_{L_r^2}^2 + \kappa^2 \|\partial_r \operatorname{div} \cdot\|_{L_r^2}^2$$

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THEOREM 2 Well-posedness of the Augmented formula

The augmented formula (PDE on (ζ, q) $(R, +\infty)$ + ODE on $(\delta, \dot{\delta}, \zeta, \dot{\zeta})$ at $r = R$) is well-posed in $H_r \times H_r^1 \times \mathbb{R}^4$ for time order $T_{\max} = O(\min(\varepsilon^{-1} \kappa, \varepsilon^{-1/2}))$.

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THEOREM 3 Decay at ∞

$$\delta \in H^2(\mathbb{R}^+) \quad \text{but} \quad \forall \beta \in (0, 2), \delta, \dot{\delta}, \ddot{\delta} \notin L^2(t^\beta dt, \mathbb{R}^+).$$

Also, for large time scales:

$$\forall k \in \{0, 1, 2\}, \forall 0 < \rho \ll 1, t^{-1/2-\rho} \lesssim |\delta^{(k)}(t)|$$

PART II

Numerical simulations

The augmented formula reads:

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- Computation of δ and ζ

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The augmented formula reads:

$$\left\{ \begin{array}{l} \partial_t \zeta + \operatorname{div} q = 0, \quad r > R \\ \kappa^2 \ddot{\zeta} + \zeta = \mathcal{R}\zeta - R\kappa \ddot{G}(r/\kappa), \quad r \geq R \\ \tilde{m} \ddot{\delta} + \delta = \kappa^2 \ddot{\zeta} + \zeta, \\ \underline{q} = -R\dot{\delta}, \end{array} \right. \quad \text{with} \quad \left\{ \begin{array}{l} (1 - \kappa^2 d_r \partial_r) \mathcal{R}u = u, \\ \underline{\partial_r \mathcal{R}u} = 0. \end{array} \right.$$

Therefore the computation of ζ and q are decoupled:

$$\left\{ \begin{array}{l} \kappa^2 \ddot{\zeta} + \zeta = \mathcal{R}\zeta - \kappa R \ddot{G}(r/\kappa), \quad r \geq R \\ M \ddot{\delta} + \delta = \underline{\mathcal{R}\zeta}, \end{array} \right. + \left\{ \begin{array}{l} \partial_t \zeta + \operatorname{div} q = 0, \quad r > R \\ \underline{q} = -\frac{R}{2} \dot{\delta}. \end{array} \right.$$

- Computation of $\mathcal{R}\zeta$ (depending on the dimension)
- Computation of δ and ζ
- Reconstruction of q (Optionnal)

PART II

Numerical simulations

The augmented formula reads:

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$$\left\{ \begin{array}{l} \kappa^2 \ddot{\zeta} + \zeta = \mathcal{R}\zeta - \frac{R}{2} M^{-1} (\underline{\mathcal{R}\zeta} - \delta) G(r/\kappa), \\ M \ddot{\delta} + \delta = \underline{\mathcal{R}\zeta}. \end{array} \right.$$

DISCRETIZATION

$$\begin{cases} \kappa^2 \frac{\zeta_i^{n+1} - 2\zeta_i^n + \zeta_i^{n-1}}{\Delta t^2} + (I - \mathfrak{R}_1)\zeta_i^n = M^{-1}((\mathfrak{R}_1\zeta^n)_0 - \delta^n)G_i, & i \in \{1, \dots, N\}, \\ \frac{\delta^{n+1} - 2\delta^n + \delta^{n-1}}{\Delta t^2} = M^{-1}((\mathfrak{R}_1\zeta^n)_0 - \delta^n), \end{cases}$$

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THEOREM 3 Energy inequality on the scheme

Let $\kappa > 0$ and $\Delta t \lesssim \kappa, \Delta x \lesssim \kappa$. If \mathcal{R} satisfies $\|\mathcal{R}u\|_{h_\kappa^1} < \|u\|_{l^2}$ and $\|\underline{\mathcal{R}u}\| < \|u\|_{l^2}$, then the time scheme satisfies the discrete energy inequality:

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with $\mathfrak{E}^{n+1/2} = E_{\text{solid}}^{n+1/2} + E_{\text{fluid}}^{n+1/2}$, $E_{\text{solid}}^{n+1/2} := \frac{(v^{n+1/2})^2}{2} + \frac{M}{2} (\delta^{n+1/2})^2$, where the speed is $v^{n+1/2} := \frac{\delta^{n+1} - \delta^n}{\Delta t}$ and the mean position is $\delta^{n+1/2} := \frac{\delta^{n+1} + \delta^n}{2}$ and $E_{\text{fluid}}^{n+1/2} := \frac{\kappa^2 \|S^n\|_{l^2}^2}{2} + \frac{1}{2} \|\zeta^{n+1} + \zeta^n\|_{l^2}^2$, where $S^n = \frac{\zeta^{n+1} - \zeta^n}{\Delta t}$.

SUMMARY

$$\begin{cases} \kappa^2 \frac{\zeta_i^{n+1} - 2\zeta_i^n + \zeta_i^{n-1}}{\Delta t^2} + (I - \mathcal{R})\zeta_i^n = M^{-1}((\mathcal{R}\zeta^n)_0 - \delta^n)G_i, & i \in \{1, \dots, N\}, \\ \frac{\delta^{n+1} - 2\delta^n + \delta^{n-1}}{\Delta t^2} = M^{-1}((\mathcal{R}\zeta^n)_0 - \delta^n), \end{cases}$$

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Important points:

- Easily adaptable with the dimension,

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- Easily adaptable with the dimension,
- Discretization of \mathcal{R} as an elliptic problem,
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- CFL of the form:

$$\Delta t \lesssim \kappa \quad \& \quad \Delta x \lesssim \kappa.$$

NUMERICAL SIMULATIONS

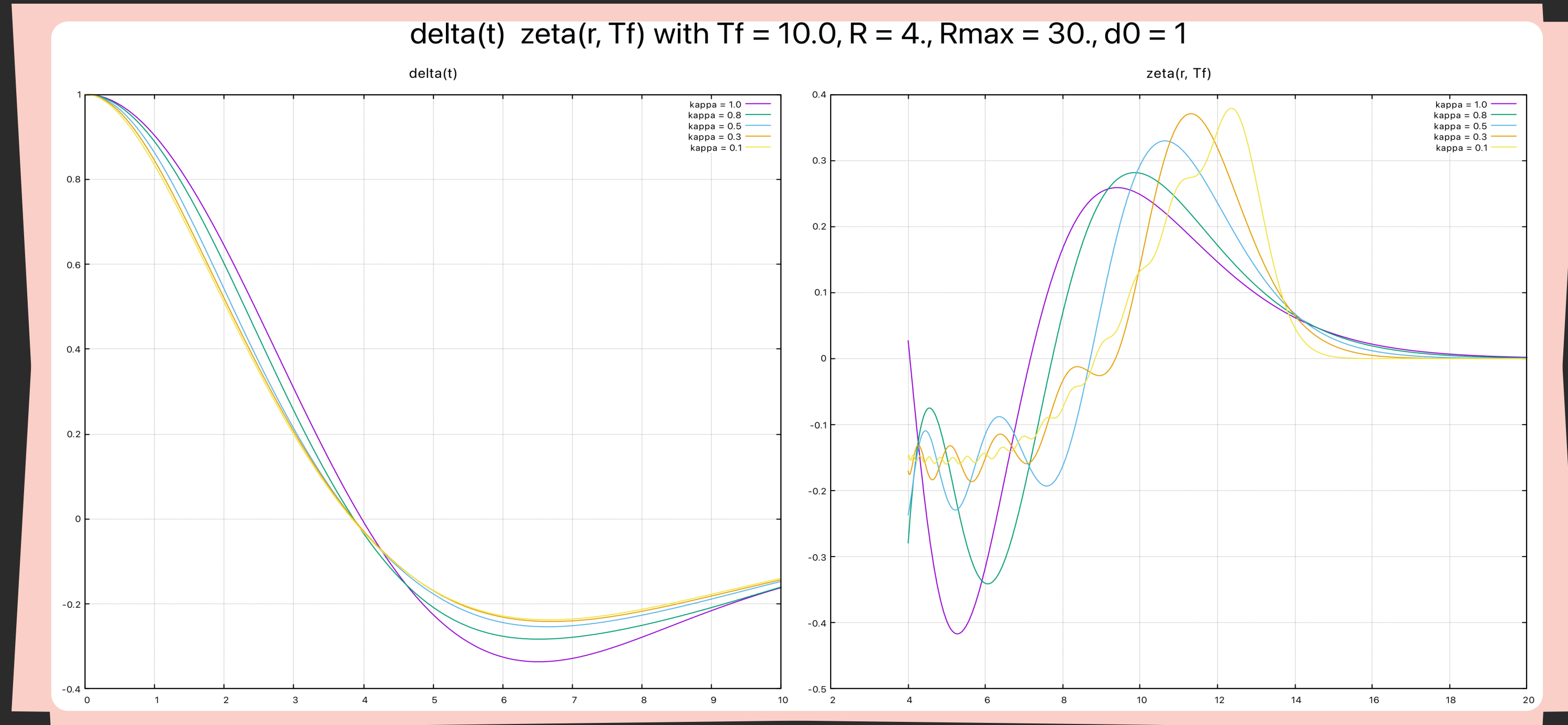


Figure - Simulations with different values of κ

NUMERICAL SIMULATIONS

Small value of κ

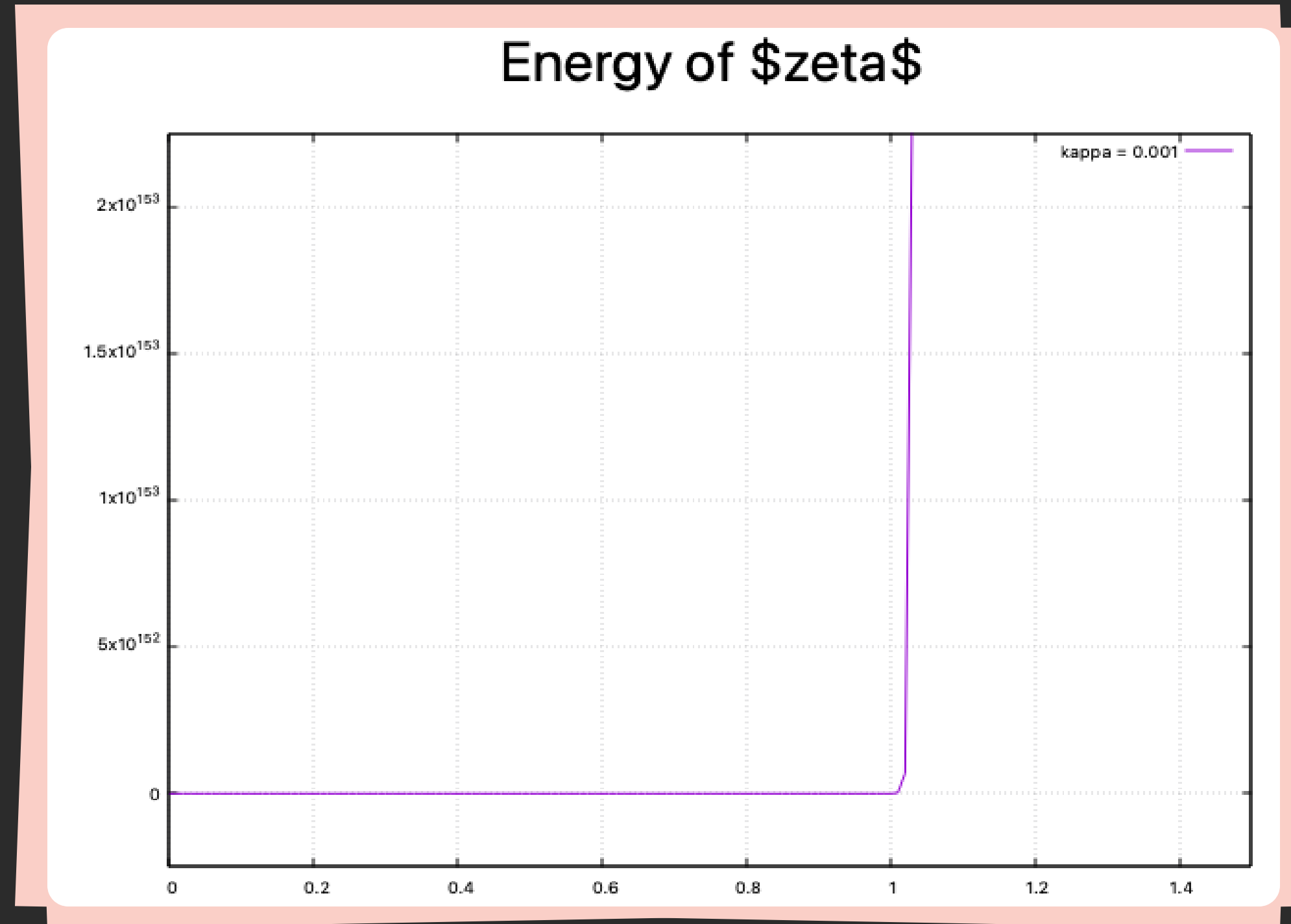


Figure - Simulations with $\kappa = 0.001$

PART III

Overpass the small values of κ in 1D

$$\begin{cases} \kappa^2 \ddot{\zeta} + \zeta = \mathcal{R}\zeta - \frac{R}{2} M^{-1}(\underline{\mathcal{R}\zeta} - \delta)G(r/\kappa), \\ M\ddot{\delta} + \delta = \underline{\mathcal{R}\zeta}. \end{cases}$$

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$$\forall k \in \mathbb{N}, \kappa^2 \hat{\ddot{\zeta}}_k + \kappa^2 \omega_k^2 \hat{\zeta}_k = c\kappa^2 (\mathcal{R}\zeta - \delta) \frac{1}{1 + \kappa^2 k^2}, \quad \omega_k^2 = \frac{k^2}{1 + \kappa^2 k^2}$$

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\Rightarrow expression of $\mathcal{R}\zeta$ for all t as

$$\forall t > 0, \mathcal{R}\zeta = \mathcal{R}\zeta^{\text{homog}} + \int_0^t K(s-t)(\mathcal{R}\zeta(s) - \delta(s)) ds$$

Discretization:

$$\forall k \in \mathbb{N}, \begin{cases} \hat{\zeta}_k^{n+1} = \cos(\omega_k \Delta t) \hat{\zeta}_k^n + \frac{\sin(\omega_k \Delta t)}{\omega_k} \hat{\dot{\zeta}}_k^n + \frac{c}{1+\kappa^2 k^2} (\underline{\mathcal{R}\zeta}^n - \delta^n) \frac{1-\cos(\omega_k \Delta t)}{\omega_k^2}, \\ \hat{\dot{\zeta}}_k^{n+1} = -\omega_k \sin(\omega_k \Delta t) \hat{\zeta}_k^n + \cos(\omega_k \Delta t) \hat{\dot{\zeta}}_k^n - \frac{c}{1+\kappa^2 k^2} (\underline{\mathcal{R}\zeta}^n - \delta^n) \frac{\sin(\omega_k \Delta t)}{\omega_k}. \end{cases}$$

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$$\begin{pmatrix} \delta \\ \dot{\delta} \end{pmatrix}^{n+1} = \begin{pmatrix} 1 & \Delta t \\ -\Delta t M^{-1} & 1 \end{pmatrix} \begin{pmatrix} \delta \\ \dot{\delta} \end{pmatrix}^n + \Delta t \begin{pmatrix} 0 \\ M^{-1} \underline{\mathcal{R}\zeta}^n \end{pmatrix}.$$

NUMERICAL SIMULATIONS

Comparison of the 2 methods

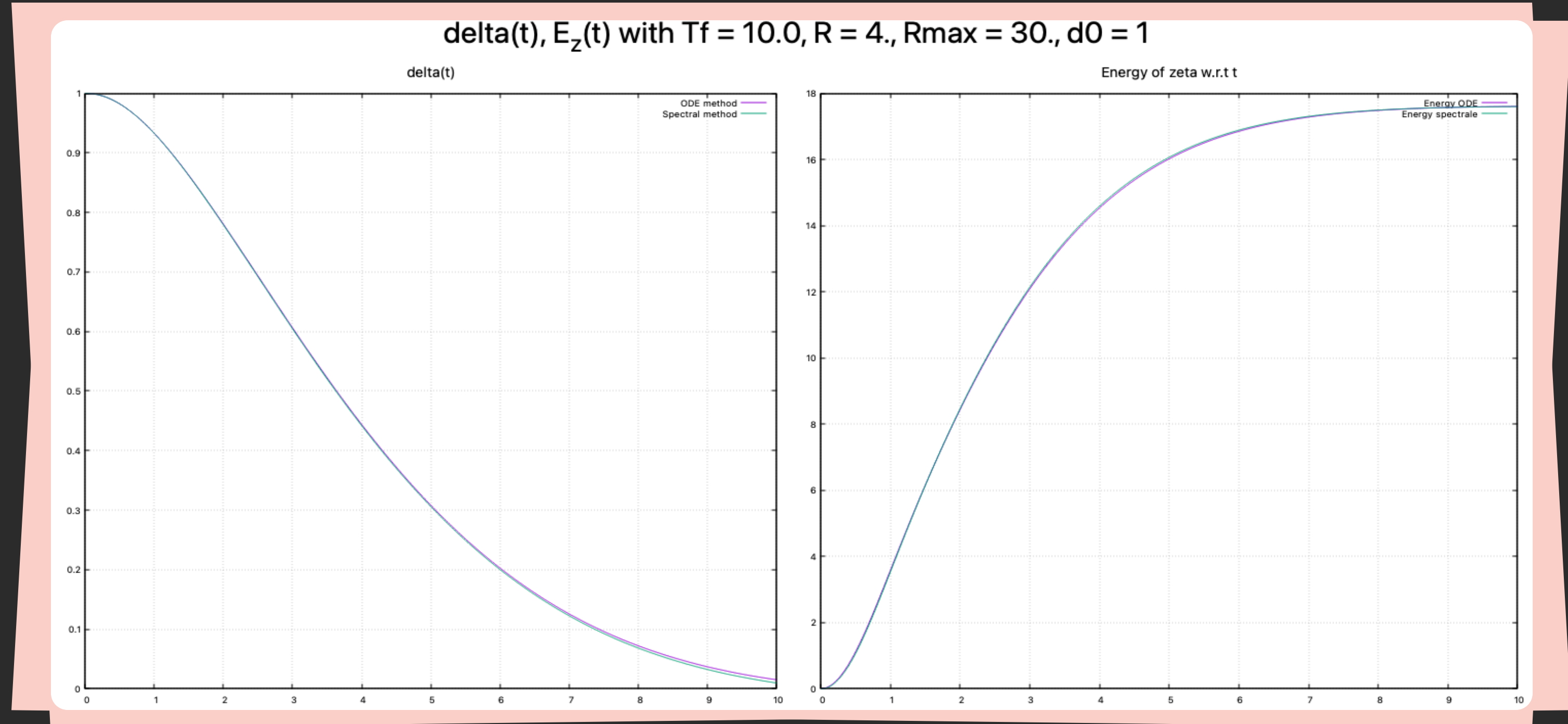


Figure - Comparaison of the methods with $\kappa = 0.3$

NUMERICAL SIMULATIONS

Small value of κ with the spectral method

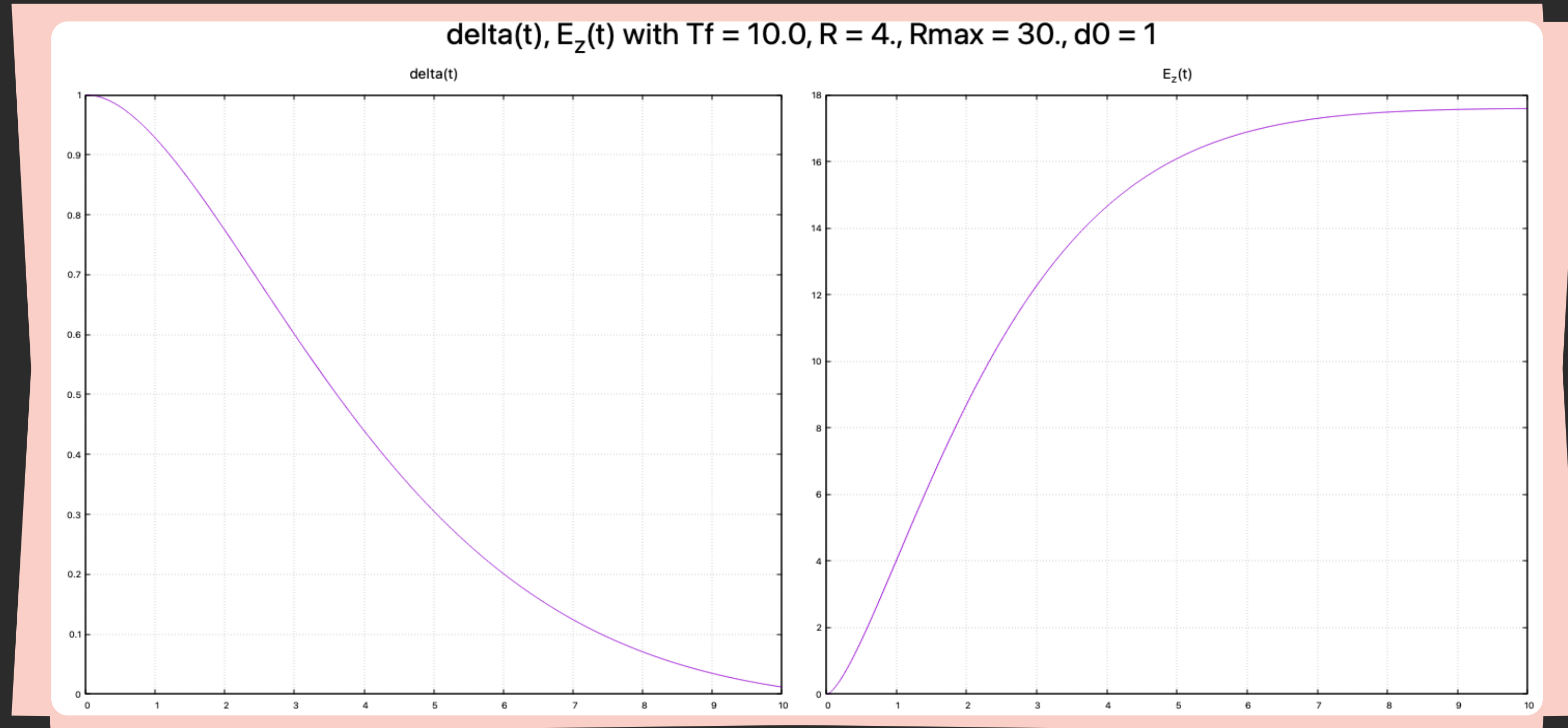


Figure - Spectral method with $\kappa = 10^{-5}$

CONCLUSIONS

& perspectives

CONCLUSIONS

& perspectives

- Non-linear case,

CONCLUSIONS

& perspectives



- Non-linear case,
- Flux scheme for the numerical simulations,

CONCLUSIONS

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- Non-linear case,
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- 2D spectral method.

REFERENCES

- Article:  Freely floating cylinder on a 3D fluid governed by the Boussinesq equations in the axisymmetric without swirl case, G.Beck, [E.Contentin](#), L.Martaud (2025)
- Proceeding:  The return to the equilibrium of a floating cylinder in the Boussinesq regime, G.Beck, [E.Contentin](#), L.Martaud (2026)

Thank you!

Slides created using reveal.js



Template

Alan Riquier, postdoctoral at Fields Institute.