

# Generating functions for variational integrators

Oscar Cosserat

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Linear Lagrangian spaces

Variational and Hamiltonian dynamics

Hamiltonian dynamics and symplectic integrators

Euler-Lagrange dynamics and variational integrators

Conclusion and perspectives

## Symplectic vector spaces

$V$  a real vector space,  $\dim V = 2d$ .

### Definition (Symplectic form)

It is a skew-symmetric non-degenerate bilinear form  $\langle \cdot, \cdot \rangle$  on  $V$ .

### Example (Position-momenta phase space)

$X$  any vector space,  $V = X \times X^*$ ,  $\langle (a_1, a_2), (b_1, b_2) \rangle = b_2(a_1) - a_2(b_1)$ .

Set  $J = \begin{pmatrix} 0_{d \times d} & I_d \\ -I_d & 0_{d \times d} \end{pmatrix}$  its matrix:  $\langle a, b \rangle = a^T \cdot J \cdot b$ .

### Example (Graph of a map $V \rightarrow V$ )

$(V, J)$  symplectic vector space  $\Rightarrow (V \times \overline{V}, J \times -J)$  again symplectic.

### Definition (Symplectomorphism $\phi: (V_1, \langle \cdot, \cdot \rangle_1) \rightarrow (V_2, \langle \cdot, \cdot \rangle_2)$ )

It is a linear map  $\phi: V_1 \rightarrow V_2$  s.t.  $\forall a, b \in V_1, \langle \phi(a), \phi(b) \rangle_2 = \langle a, b \rangle_1$ .

### Proposition (Symplectomorphy)

$$X \times X \times (X \times X)^* \simeq X \times X^* \times \overline{X \times X^*}$$

# Lagrangian subspaces, В. И. Арнольд<sup>1</sup>, 1967

## Definition

A Lagrangian subspace  $L$  of  $(V, \langle \cdot, \cdot \rangle)$  is a vector subspace that is isotropic and of dimension  $d$ .

## Example ( $V = X \times X^*$ , generating functions)

- ▶  $L = X \times \{0_{X^*}\}$
- ▶  $L = \{(x, \Psi(x)) \in X \times X^*, x \in X\}$ ,  $\Psi: X \rightarrow X^*$  symmetric.

## Example ( $V \times \bar{V}$ , symplectomorphisms)

- ▶ the diagonal  $L = \{(v, v) \in V \times V, v \in V\}$
- ▶  $L = \{(v, \phi(v)) \in V \times V\}$ ,  $\phi: (V, \langle \cdot, \cdot \rangle) \rightarrow (V, \langle \cdot, \cdot \rangle)$ .

## Remark (Hamiltonian dynamics = generating functions)

*Those examples relate to one another through the symplectomorphy (1).*

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<sup>1</sup>Characteristic class entering in quantization condition, Arnol'd, 1967

## Newton's second law, 1687

$(F_i)_i: \mathbb{R}^d \rightarrow \mathbb{R}^d$  a force admitting a potential  $V: \mathbb{R}^d \rightarrow \mathbb{R}$  and  $m > 0$  the mass of the particule.

$$\begin{aligned} m\ddot{q}_i = F_i(q_1, \dots, q_d) &\Leftrightarrow \begin{pmatrix} \dot{q} \\ v \end{pmatrix} = \begin{pmatrix} \dot{q} \\ \frac{1}{m} \nabla V(q) \end{pmatrix} & (1) \\ &\Leftrightarrow \begin{pmatrix} \dot{q} \\ p \end{pmatrix} = \begin{pmatrix} \dot{q} \\ \nabla V(q) \end{pmatrix} \\ &\Leftrightarrow \dot{x} = J \cdot \nabla_x H \end{aligned}$$

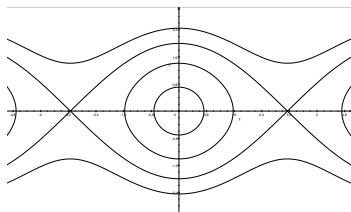
where

- ▶  $x = (q, p) \in \mathbb{R}^d \times (\mathbb{R}^d)^*$  a point of the phase space,
- ▶  $J = \begin{pmatrix} 0_{d \times d} & Id \\ -Id & 0_{d \times d} \end{pmatrix}$  is the symplectic form,
- ▶  $H(q, p) = \frac{1}{2m} \sum_{i=1}^d p_i^2 - V(q)$  the Hamiltonian.

# Symplecticity

## Proposition (Energy conservation)

$$\frac{\partial}{\partial t} H(q(t), p(t)) = 0.$$



Phase plan of  $\ddot{q} = -\frac{g}{L} \sin(q)$

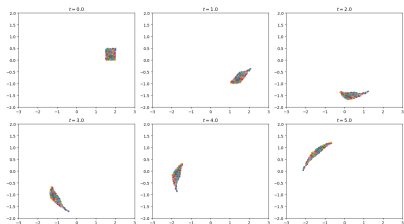
$$H(q, p) = \frac{p^2}{2mL^2} + mgL(1 - \cos q)$$

$$\phi_t^H: \begin{array}{l} \mathbb{R}^d \times (\mathbb{R}^d)^* \rightarrow \mathbb{R}^d \times (\mathbb{R}^d)^* \\ (q(0), p(0)) \mapsto ((q(t), p(t))) \end{array}$$

## Proposition

*Any Hamiltonian flow is symplectic:*

$$\text{Jac}(\phi_t^H)^T \cdot J \cdot \text{Jac}(\phi_t^H) = J$$



$d = 1$ : volume preservation

source : furnstahl.github.io

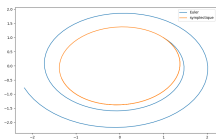
# Symplectic integrators

## Definition (An integrator)

It is a family  $\varphi_{\Delta t}: x_n \mapsto x_{n+1}$  parametrized by the time-step  $\Delta t$ .  
 $\varphi_{\Delta t}$  is symplectic if  $\mathbf{Jac}(\varphi_{\Delta t})^T \cdot J \cdot \mathbf{Jac}(\varphi_{\Delta t}) = J$ .

## Example (Symplectic Euler method, DeVogelaere, 1956)

$$\begin{pmatrix} q_{n+1} \\ p_{n+1} \end{pmatrix} = \begin{pmatrix} q_n + \Delta t \frac{\partial H}{\partial p}(q_n, p_{n+1}) \\ p_n - \Delta t \frac{\partial H}{\partial q}(q_n, p_{n+1}) \end{pmatrix}$$



$$H(q, p) = \frac{p^2 + q^2}{2},$$

$\Delta t = 0.1, n = 100$  itérations

## Theorem (Quasi-first integral, Benettin et Giorgilli, 1994)

Under some assumptions,  $\exists (H_\epsilon)_\epsilon, C > 0, \epsilon^* > 0$  s.t.

$$\forall n \in \mathbb{N}, \forall \epsilon < \epsilon^*, |H_\epsilon(\varphi_\epsilon^n(q, p)) - H_\epsilon(q, p)| \leq Cn\epsilon \exp\left(-\frac{\epsilon^*}{\epsilon}\right) \quad (2)$$

## Euler-Lagrange equations, 1750's

Starting again from Newtonian mechanics (1):

$$\begin{aligned} m\ddot{q}_i = F_i(q_1, \dots, q_d) &\Leftrightarrow \begin{pmatrix} \dot{q} \\ v \end{pmatrix} = \begin{pmatrix} \frac{1}{m} \nabla^v V(q) \end{pmatrix} \\ &\Leftrightarrow \frac{d}{dt} \frac{\partial L}{\partial v} = \frac{\partial L}{\partial q} \\ &\Leftrightarrow \delta \int L = 0 \end{aligned}$$

where

- ▶  $(q, v)$  position and velocity of the particle,
- ▶  $L(q, v) = \frac{1}{2m} \sum_{i=1}^d v_i^2 + V(q)$  the Lagrangian.

# Generating functions

## Definition (The action)

$$S_t: \mathbb{R}^d \times \mathbb{R}^d \rightarrow \mathbb{R} \quad (3)$$

$$(q_0, q_1) \mapsto \int_0^t L(q(s), \dot{q}(s)) ds$$

where  $s \in [0, t] \mapsto q(s)$  the extremal path s.t.  $\begin{cases} q(0) = q_0, \\ q(t) = q_1 \end{cases}$ .

## Remark

$t$  is small,  $q_1$  close to  $q_0$ .

**The graph of the generating function (3) is the graph of the Hamiltonian flow !**

$$\begin{array}{ccc} \text{Graph}(dS_t) & \mapsto & \text{Graph}(\phi_t^H) \\ \cap & & \cap \\ T^*(\mathbb{R}^d \times \mathbb{R}^d) & \xrightarrow{\sim} & T^*\mathbb{R}^d \\ (q_0, q_1, \frac{\partial S_t}{\partial q_0}(q_0, q_1), \frac{\partial S_t}{\partial q_1}(q_0, q_1)) & \mapsto & (q_0, p_0), \quad \phi_t^H(q_0, p_0) \end{array}$$

## Variational integrators<sup>2</sup>

Discretize  $S_t$ :

$$\int_0^t L(q(s), \dot{q}(s)) ds \approx \int_0^t L(q_0, \frac{q_1 - q_0}{t}) ds$$

and obtain the discrete action

$$\hat{S}_t: (q_0, q_1) \mapsto tL(q_0, \frac{q_1 - q_0}{t}).$$

Then, start from, e.g.  $(q_0, q_1)$  and iterate:

$$\begin{aligned} p_0 &= \partial_1 \hat{S}_t(q_0, q_1) \\ p_1 &= \partial_2 \hat{S}_t(q_0, q_1) = \partial_1 \hat{S}_t(q_1, q_2) \\ &\dots \end{aligned} \tag{4}$$

Symplectic tools  $\Rightarrow$  the numerical method (4) has the same stability theory than with symplectic integrators, estimates (2) etc...

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<sup>2</sup>Discrete mechanics and variational integrators, Marsden and West, 2001

## Composition of Lagrangian spaces and consequences

Hamiltonian flows	$\phi^{H_3} = \phi^{H_1} \circ \phi^{H_2}$
Trajectories	Concatenation of paths
Generating functions	$S_3(q_0, q_2) = \text{extr}_{q_1} (S_1(q_0, q_1) + S_2(q_1, q_2))$

### Composition of Lagrangian spaces in mechanics

⇒ This provides a geometric framework towards:

Symplectic multi-step methods:

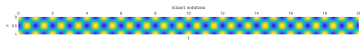
- ▶ vibration of molecules
- ▶ delayed ODEs



Ethylene  
fig.: Wikipedia

Variational integrators for field theories:

- ▶ wave equation,
- ▶ Poisson equation,
- ▶ Geometrically exact beam theory on  $SO(3)$



An oscillation mode of the wave  
equation  
fig.: R. Sato

## Conclusion and perspectives

- ▶ Hamiltonian and variational structures of an equation provide time discretizations with long run stability and large time steps.
- ▶ For continuous media, the study of those structure is a prerequisite to the use of such methods.

### **Symplectic methods in beam theory with L. Le Marrec, V. Carlier, A. Patel :**

- ▶ *Timoshenko beam under finite and dynamic transformations: Lagrangian coordinates and Hamiltonian structures*, C., Le Marrec, CAM, 2025
- ▶ **ongoing**: energetic exchanges between vibration modes and study of bifurcations

### **Variational integrators for field theories with S. Leyendecker, D. M. de Diego, R. Sato, T. Wang :**

- ▶ **ongoing**: boundary Lagrangians and application to field theories